## B.Tech. Degree VII S'emester (Supplementary) Examination June 2006

## IT//CS/EE 705 (A) DIGITAL IMAGE PROCESSING

WHO3 0 286		(2002 Admissions onwards)	
SO OZ MINE:	3 Hours	Maximum Mark	s: 100
I	a)	Differentiate between image enhancement and image restoration.	(10)
	b)	State the principle of image data compression. Where is it required in image processing.  OR	(10)
II	a)	Define: (i) Separable systems	
		(ii) 2-D Fourier transform	
	1.3	(iii) Stationary process	(9)
	b)	Define Kronecker product of 2 matrices and find the Kronecker product of A&B where	
		$A = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \text{ and } B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$	(11)
		$\begin{bmatrix} 1 & -1 \end{bmatrix}$ $\begin{bmatrix} 3 & 4 \end{bmatrix}$	(11)
Ш	a)	Explain the following terms:	
	,	(i) Match band effect	
		(ii) MTF of visual system	
		(iii) Luminance, brightness and contrast (12)	
	b)	Describe the colour vision model.	(8)
IV	a)	OR State and explain 2-D sampling theorem.	(6)
•	b)	State the practical limits with respect to image sampling and reconstruction	(6)
	c)	What is colour matching? Explain the important laws of colour matching.	(8)
v	a)	What is a unitary transform? Explain with an example. State its properties.	(12)
*	b)	Generate Hadmard transform of order 3.	(8)
	,	OR	` '
VI	a)	Define 2-D Discrete Cosine Transform and state its properties.	(12)
	b)	State the properties of Haar Transform.	(8)
VII		Explain in detail any spatial domain methods for image enhancement.  OR	(20)
VIII	a)	Explain the basic principle of homo morphic filtering.	(8)
1	b)	Write short notes on colour image enhancement.	(6)
	c)	Explain linear interpolation.	(6)
IX	a)	Explain different techniques used for feature extraction.	(12)
	b)	Explain the principle of operation of edge detectors.	(8)
x	a)	Explain with block diagram a computer vision system.	(8)
-•	b)	Describe clearly how lines and spots can be detected in an image.	(12)