

*This question paper contains 5 printed pages.*

3335

Your Roll No. ....

**B. Tech. (EEEC) / I**

**J**

**Paper V— POWER APPARATUS  
(EEC-105)**

*Time : 3 hours*

*Maximum Marks : 70*

*(Write your Roll No. on the top immediately  
on receipt of this question paper.)*

*Q. No. 1 is compulsory. Answer any four  
from the remaining.*

*All questions carry equal marks.*

1. (a) Large rating transformers have higher efficiencies. Why?
- (b) In construction of transformers, why are low voltage windings placed near the magnetic core?
- (c) What transformer parameters are determined by the short circuit test? Sketch the approximate equivalent circuit under short circuit condition.
- (d) Explain, why the current in the primary of a transformer increases when a load is placed across the secondary winding.
- (e) State two reasons for skewing rotor slots in a squirrel cage induction motor.

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- (f) A 50 Hz, 4 pole, 415 V, 3 phase induction motor operating at rated conditions has a speed of 1440 rpm. What is the frequency of rotor induced emf?
- (g) Write two functions of damper winding in a synchronous motor. 2×7
2. (a) Draw approximate equivalent circuits of a transformer referred to primary and secondary windings and express the impedances, voltages and currents for the respective winding sides. 7
- (b) Determine the parameters of the approximate equivalent circuit referred to the high voltage (HV) side of a 100 kVA, 4400/220 V, 50 Hz transformer whose O.C. and S.C. test results are given as:
- O.C. Test* : When 4400 V is supplied to the HV side with the low voltage winding kept open, the input power and current are 1010 W and 0.5 A respectively.
- S.C. Test* : When 353 V is supplied to the HV side with low voltage side short-circuited, the primary draws full load current and absorbs a power of 2100 W. 7
3. (a) Define efficiency of a transformer under any operating condition and derive condition for the maximum efficiency for constant values of the terminal voltage and load power factor angle. 7
- (b) A 300 kVA transformer has a core-loss of 1.5 kW and a full load copper loss of 4.5 kW.

- (i) Calculate its efficiency at half as well as full load at unity power factor.
- (ii) Determine the load for which efficiency is maximum and calculate the corresponding efficiency at unity power factor. 7
4. (a) What are two different types of synchronous machines? Write necessary expressions and sketch power-angle characteristics for both types. 7
- (b) The stator of a 3 phase alternator has nine slots per pole and carries a balanced three-phase double layer winding. The coils are short pitched and the coil pitch is  $7/9$ , that is each coil spans seven slots. Determine the winding factor. 7
5. (a) Why is a synchronous motor not self starting? State how a synchronous motor is started. 7
- (b) Draw an approximate equivalent circuit of a 3-phase induction motor and determine expressions for slip at which the maximum torque occurs and value of the maximum torque. Sketch the torque-speed curves for a wound-rotor induction motor and show the effect of increasing rotor resistance on the torque-speed characteristic of this motor. 7
6. (a) A 3 phase, 415 V, 50 Hz, four pole, Y-connected induction motor operating at full load runs at 1425 rpm. The rotor resistance and reactance per

phase are  $0.4 \Omega$  and  $4 \Omega$ , respectively, and the effective rotor-stator turns ratio is  $0.8 : 1$ .

Calculate:

- (i) the full load torque
  - (ii) the power output, if mechanical losses are  $480 \text{ W}$
  - (iii) the maximum torque
  - (iv) the speed at which maximum torque occurs
  - (v) torque at starting. 7
- (b) With help of neat torque-speed characteristics differentiate the operation/performance of single-phase, split phase, capacitor start and run, capacitor start motor, two capacitor motor and shaded pole motors. 7
7. (a) What is an universal motor? Discuss its torque-speed, efficiency and power factor characteristics for AC and DC operations. 7
- (b) A  $220 \text{ V}$ ,  $50 \text{ Hz}$ , 4-pole, single phase induction motor has the following equivalent circuit parameters at stand-still:
- $$R_1 = 2 \Omega, \quad R_2 = 4 \Omega, \quad X_1 = 2.6 \Omega, \quad X_2 = 2.0 \Omega,$$
- $$X_m = 70 \Omega.$$
- (i) Draw equivalent circuit of the motor when it is running at a speed of  $1425 \text{ rpm}$ .

- (ii) What are the frequencies of the rotor currents induced by the forward field and the backward field? 7

8. Write short notes on any *two* of the following:

- (i) Double revolving field theory
- (ii) Two phase AC servomotor
- (iii) Stepper motor
- (iv) Static Kramer System. 2×7