

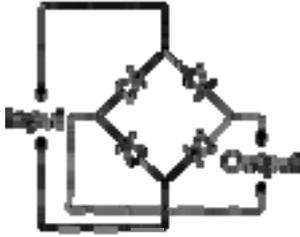
ELECTRONICS & COMMUNICATION ENGINEERING

ONE MARK QUESTIONS

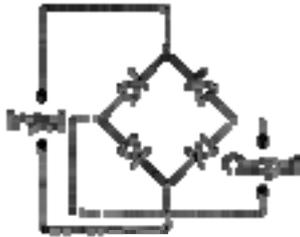
- An independent voltage source in series with an impedance $Z_s = R_s + jX_s$ delivers a maximum average power to a load impedance Z_L when
 - $Z_L = R_s + jX_s$
 - $Z_L = R_s$
 - $Z_L = jX_s$
 - $Z_L = R_s - jX_s$
- The RC circuit shown in the figure is



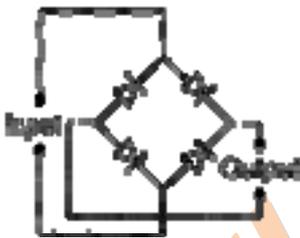
- a low-pass filter
 - a high-pass filter
 - a band-pass filter
 - a band-reject filter
- The electron and hole concentrations in an intrinsic semiconductor are n_i per cm^3 at 300 K. Now, if acceptor impurities are introduced with a concentration of N_A per cm^3 (where $N_A \gg n_i$) the electron concentration per cm^3 at 300 K will be
 - n_i
 - $n_i + N_A$
 - $N_A - n_i$
 - $\frac{n_i^2}{N_A}$
 - In a p^+n junction diode under reverse bias, the magnitude of electric field is maximum at
 - the edge of the depletion region on the p-side
 - the edge of the depletion region on the n-side
 - the p^+n junction
 - the centre of the depletion region on the n-side
 - The correct full wave rectifier circuit is
 -



(b.)



(c.)



(d.)



6. In a trans-conductance amplifier, it is desirable to have
- a large input resistance and a large output resistance
 - a large input resistance and a small output resistance
 - a small input resistance and a large output resistance
 - a small input resistance and a small output resistance
7. $X = 01110$ and $Y = 11001$ are two 5-bit binary numbers represented in two's complement format. The sum of X and Y represented in two's complement format using 6 bits is
- 100111
 - 001000
 - 000111
 - 101001
8. The Boolean function $Y = AB + CD$ is to be realized using only 2-input NAND gates. The minimum number of gates required is
- 2

- (b.)3
(c.)4
(d.)5
9. If the Laplace transform of a signal $y(t)$ is $Y(s) = \frac{1}{s(s-1)}$, then its final value is
- (a.) -1
(b.) 0
(c.) 1
(d.) Unbounded
10. If $R(\tau)$ is the autocorrelation function of a real, wide-sense stationary random process, then which of the following is NOT true?
- (a.) $R(\tau) = R(-\tau)$
(b.) $|R(\tau)| \leq R(0)$
(c.) $R(\tau) = -R(-\tau)$
(d.) The mean square value of the process is $R(0)$
11. If $S(f)$ is the power spectral density of a real, wide-sense stationary random process, then which of the following is ALWAYS true?
- (a.) $S(0) \geq S(f)$
(b.) $S(f) \geq 0$
(c.) $S(-f) = -S(f)$
(d.) $\int_{-\infty}^{\infty} S(f) df = 0$
12. If the closed-loop transfer function of a control system is given as $T(s) = \frac{s-5}{(s+2)(s+3)}$, then it is
- (a.) an unstable system
(b.) a minimum phase system
(c.) an uncontrollable system
(d.) a non-minimum phase system
13. If E denotes expectation, the variance of a random variable X is given by
- (a.) $E[X^2] - E^2[X]$
(b.) $E[X^2] + E^2[X]$
(c.) $E[X^2]$
(d.) $E^2[X]$

14. A plane wave of wavelength λ is travelling in a direction making an angle 30° with positive x-axis and 90° with positive y-axis. The \vec{E} field of the plane wave can be represented as (E_0 is a constant)

(a.) $\vec{E} = \hat{y} E_0 e^{j\left(\omega t - \frac{\sqrt{3}\pi}{\lambda}x - \frac{\pi}{\lambda}z\right)}$

(b.) $\vec{E} = \hat{y} E_0 e^{j\left(\omega t - \frac{\pi}{\lambda}x - \frac{\sqrt{3}\pi}{\lambda}z\right)}$

(c.) $\vec{E} = \hat{y} E_0 e^{j\left(\omega t + \frac{\sqrt{3}\pi}{\lambda}x + \frac{\pi}{\lambda}z\right)}$

(d.) $\vec{E} = \hat{y} E_0 e^{j\left(\omega t - \frac{\pi}{\lambda}x + \frac{\sqrt{3}\pi}{\lambda}z\right)}$

15. If C is a closed curve enclosing a surface S , then the magnetic field intensity \vec{H} , the current density \vec{J} and the electric flux density \vec{D} are related by

(a.) $\iint_s \vec{H} \cdot \vec{ds} = \oint_c \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot \vec{dl}$

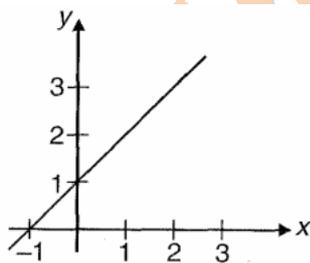
(b.) $\int_c \vec{H} \cdot \vec{dl} = \oiint_s \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot \vec{ds}$

(c.) $\oiint_s \vec{H} \cdot \vec{ds} = \int_c \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot \vec{dl}$

(d.) $\oint_c \vec{H} \cdot \vec{dl} = \iint_s \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot \vec{ds}$

16. The following plot shows a function y which varies linearly with x . The value of the integral

$$I = \int_1^2 y dx$$



- (a.) 1.0
 (b.) 2.5
 (c.) 4.0
 (d.) 5.0
17. For $|x| \ll 1$, both $\cos(x)$ and $\sin(x)$ can be approximated as
- (a.) x
 (b.) x^2

- (c.) $\frac{1}{x}$
- (d.) $\frac{1}{x^2}$
18. $\lim_{\theta \rightarrow 0} \frac{\sin(\theta/2)}{\theta}$ is
- (a.) 0.5
- (b.) 1
- (c.) 2
- (d.) Not defined
19. Which one of the following functions is strictly bounded?
- (a.) $\frac{1}{x^2}$
- (b.) e^x
- (c.) x^2
- (d.) e^{-x^2}
20. For the function e^{-x} , the linear approximation around $x = 2$ is
- (a.) $(3-x)e^{-2}$
- (b.) $1-x$
- (c.) $[3+2\sqrt{2}-(1+\sqrt{2})x]e^{-2}$
- (d.) e^{-2}

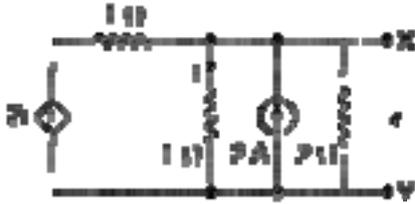
TWO MARKS QUESTIONS

21. Two series resonant filters are as shown in the figure. Let the 3-dB bandwidth of Filter 1 be B_1 and that of Filter 2 be B_2 . The value of $\frac{B_1}{B_2}$ is

- (a.) 4
- (b.) 1
- (c.) $\frac{1}{2}$

(d.) $\frac{1}{4}$

22. For the circuit shown in the figure, the Thevenin voltage and resistance looking into X-Y are



(a.) $4/3\text{V}, 2\Omega$

(b.) $4\text{V}, 2/3\Omega$

(c.) $4/3\text{ V}, 2/3\Omega$

(d.) $4\text{ V}, 2\Omega$

23. In the circuit shown, V_C is 0 volts at $t = 0$ sec. For $t > 0$, the capacitor current $i(t)$, where t is in seconds, is given by



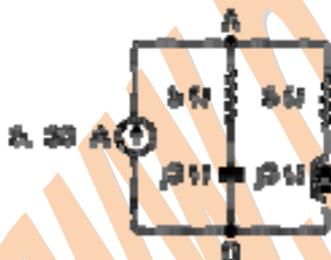
(a.) $0.50 \exp(-25t)$ mA

(b.) $0.25 \exp(-25 t)$ mA

(c.) $0.50 \exp(-12.5t)$ mA

(d.) $0.25 \exp(-6.25 t)$ mA

24. the AC network shown in the figure, the phasor voltage V_{AB} (in Volts) is



(a.) 0

(b.) $5\angle 30^\circ$

(c.) $12.5\angle 30^\circ$

(d.) $17\angle 30^\circ$

25. Group I lists four types of p-n junction diodes. Match each device in Group I with one of the options in Group II to indicate the bias condition of that device in its normal mode of operation.

Group I

A. Zener Diode

- B. Solar cell
- C. LASER diode
- D. Avalanche Photodiode

Group II

1. Forward bias
2. Reverse bias

Codes:

	A	B	C	D
(a.)	1	2	1	2
(b.)	2	1	1	2
(c.)	2	2	2	1
(d.)	2	1	2	2

26. Group I lists four different semiconductor devices. Match each device in Group I with its characteristic property in Group II.

Group I

- A. BJT
- B. MOS capacitor
- C. LASER diode
- D. JFET

Group II

1. Population inversion
2. Pinch-off voltage
3. Early effect
4. Flat-band voltage

Codes:

	A	B	C	D
(a.)	3	1	4	2
(b.)	1	4	3	2
(c.)	3	4	1	2
(d.)	3	2	1	4

27. A p^+n junction has a built-in potential of 0.8 V. The depletion layer width at a reverse bias of 1.2 V is $2 \mu\text{m}$. For a reverse bias of 7.2 V, the depletion layer width will be

- (a.) $4 \mu\text{m}$
- (b.) $4.9 \mu\text{m}$
- (c.) $8 \mu\text{m}$
- (d.) $12 \mu\text{m}$

28. The DC current gain (β) of a BJT is 50. Assuming that the emitter injection efficiency is 0.995, the base transport factor is
- 0.980
 - 0.985
 - 0.990
 - 0.995
29. For the Op-Amp circuit shown in the figure, V_0 is



- 2V
 - 1V
 - 0.5V
 - 0.5V
30. For the BJT circuit shown, assume that the β of the transistor is very large and $V_{BE} = 0.7$ V. The mode of operation of the BJT is



- cut-off
 - saturation
 - normal active
 - reverse active
31. In the OP-Amp circuit shown, assume that the diode current follows the equation $I = I_s \exp(V/V_T)$. For $V_i = 2$ V, $V_0 = V_{01}$, and for $V_i = 4$ V, $V_0 = V_{02}$. The relationship between V_{01} and V_{02} , is



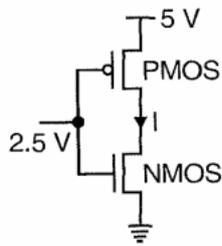
- $V_{02} = \sqrt{2} V_{01}$

(b.) $V_{02} = e^2 V_{01}$

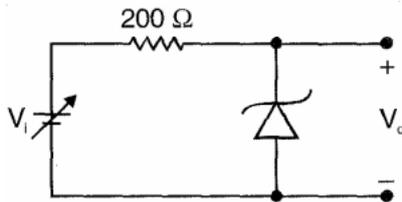
(c.) $V_{02} = V_{01} \ln 2$

(d.) $V_{01} - V_{02} = V_T \ln 2$

32. In the CMOS inverter circuit shown, if the trans-conductance parameters of the NMOS and PMOS transistors are $k_n = k_p = \mu C_{ox} \frac{W_n}{L_n} = \mu_p C_{ox} \frac{W_p}{L_p} = 40 \mu\text{A}/\text{V}^2$ and their threshold voltages are $V_{THn} = |V_{THp}| = 1 \text{ V}$, the current I is



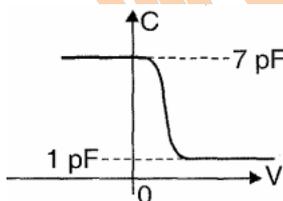
- (a.) 0 A
 (b.) 25 μA
 (c.) 45 μA
 (d.) 90 μA
33. For the Zener diode shown in the figure, the Zener voltage at knee is 7 V, the knee current is negligible and the Zener dynamic resistance is 10 Ω . If the input voltage (V_i) range is from 10 to 16 V, the output voltage (V_o) ranges from



- (a.) 7.00 to 7.29V
 (b.) 7.14 to 7.29V
 (c.) 7.14 to 7.43V
 (d.) 7.29 to 7.43V

Common Data Questions 34, 35, 36:

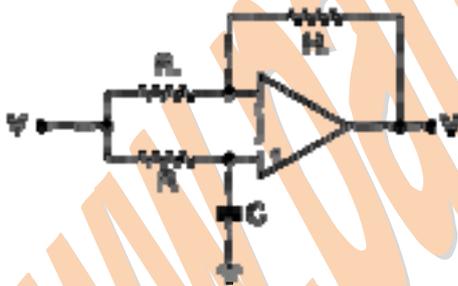
The figure shows the high-frequency capacitance-voltage (C-V) characteristics of a Metal/SiO₂/ silicon (MOS) capacitor having an area of 1 x 10 cm². Assume that the permittivities (ϵ_0, ϵ_r) of silicon and SiO₂ are 1 x 10⁻¹² F/cm and 3.5 x 10⁻¹³ F/cm respectively.



34. The gate oxide thickness in the MOS capacitor is:
- 50 nm
 - 143 nm
 - 350 nm
 - 1 μm
35. The maximum depletion layer width in silicon is:
- 0.143 μm
 - 0.857 μm
 - 1 μm
 - 1.143 μm
36. Consider the following statements about the C-V characteristics plot:
 S1: The MOS capacitor has as n-type substrate.
 S2: If positive charges are introduced in the oxide, the C-V plot will shift to the left.
 Then which of the following is true?
- Both S1 and S2 are true
 - S1 is true and S2 is false
 - S1 is false and S2 is true
 - Both S1 and S2 are false

Statement for Linked Answer Questions 37 & 38:

Consider the Op-Amp circuit shown in the figure.



37. The transfer function $V_0(s)/V(s)$ is
- $\frac{1-sRC}{1+sRC}$
 - $\frac{1+sRC}{1-sRC}$
 - $\frac{1}{1-sRC}$

(d.) $\frac{1}{1+sRC}$

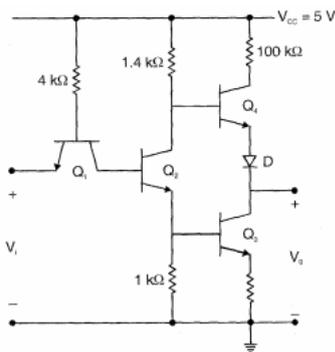
38. If $V_i = V_1 \sin(\omega t)$ and $V_o = V_2 \sin(\omega t + \phi)$, then the minimum and maximum values of ϕ (in radians) are respectively Consider the Op-Amp circuit shown in the figure.

- (a.) $-\pi/2$ and $\pi/2$
- (b.) 0 and $\pi/2$
- (c.) $-\pi$ and 0
- (d.) $-\pi/2$ and 0

39. The Boolean expression $Y = \bar{A}\bar{B}\bar{C}D + \bar{A}BC\bar{D} + AB\bar{C}\bar{D}$ can be minimized to

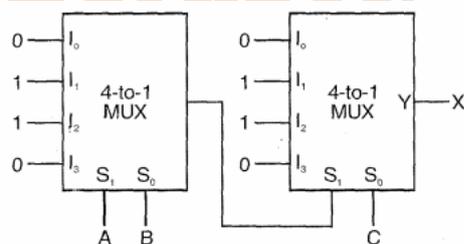
- (a.) $Y = \bar{A}\bar{B}\bar{C}D + \bar{A}B\bar{C} + A\bar{C}\bar{D}$
- (b.) $Y = \bar{A}\bar{B}\bar{C}D + BC\bar{D} + \bar{A}\bar{B}\bar{C}D$
- (c.) $Y = \bar{A}BC\bar{D} + \bar{B}\bar{C}D + \bar{A}\bar{B}\bar{C}D$
- (d.) $Y = \bar{A}BC\bar{D} + \bar{B}\bar{C}D + AB\bar{C}\bar{D}$

40. The circuit diagram of a standard TTL NOT gate is shown in the figure. When $V_i = 2.5$ V, the modes of operation of the transistors will be



- (a.) Q_1 : reverse active; Q_2 : normal active; Q_3 : saturation; Q_4 : cut-off
- (b.) Q_1 : reverse active; Q_2 : saturation; Q_3 : saturation; Q_4 : cut-off
- (c.) Q_1 : normal active; Q_2 : cut-off; Q_3 : cut-off; Q_4 : saturation
- (d.) Q_1 : saturation; Q_2 : saturation; Q_3 : saturation; Q_4 : normal active

41. In the following circuit, X is given by



- (a.) $X = \bar{A}\bar{B}\bar{C} + \bar{A}B\bar{C} + \bar{A}\bar{B}C + ABC$
- (b.) $X = \bar{A}BC + \bar{A}\bar{B}C + ABC + \bar{A}\bar{B}\bar{C}$
- (c.) $X = AB + BC + AC$

$$(d.) X = \bar{A}\bar{B} + \bar{B}\bar{C} + \bar{A}\bar{C}$$

42. The following binary values were applied to the X and Y inputs of the NAND latch shown in the figure in the sequence indicated below:

$$X = 0, Y = 1;$$

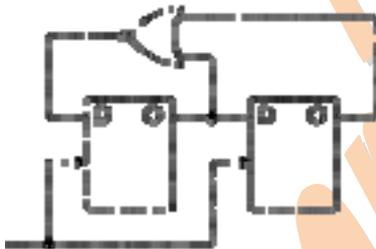
$$X = 0, Y = 0;$$

$$X = 1, Y = 1.$$

The corresponding stable P, Q outputs will be



- (a.) $P=1, Q=0; P=1, Q=0; P=1, Q=0$ or $P=0, Q=1$
 (b.) $P=1, Q=0; P=0, Q=1$ or $P=0, Q=1; P=0, Q=1$
 (c.) $P=1, Q=0; P=1, Q=1; P=1, Q=0$ or $P=0, Q=1$
 (d.) $P=1, Q=0; P=1, Q=1; P=1, Q=1$
43. For the circuit shown, the counter state (Q_1Q_0) follows the sequence

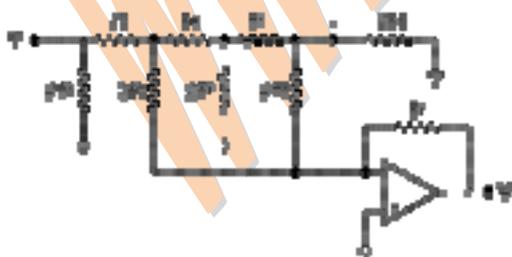


- (a.) 00,01,10,11,00...
 (b.) 00,01,10,00,01...
 (c.) 00, 01, 11,00,01...
 (d.) 00, 10, 11,00, 10...

Statement for Linked Answer

Questions 44 & 45:

In the Digital-to-Analog converter circuit shown in the figure below, $V_R = 10\text{ V}$ and $R = 10\text{ k}\Omega$.



44. The current i is
- (a.) $31.25 \mu\text{A}$
 - (b.) $62.5 \mu\text{A}$
 - (c.) $125 \mu\text{A}$
 - (d.) $250 \mu\text{A}$
45. The voltage V_0 is
- (a.) -0.781 V
 - (b.) -1.562 V
 - (c.) -3.125 V
 - (d.) -6.250 V
46. The 3-dB bandwidth of the low-pass signal $e^t u(t)$, where $u(t)$ is the unit step function, is given by
- (a.) $\frac{1}{2\pi} \text{ Hz}$
 - (b.) $\frac{1}{2\pi} \sqrt{\sqrt{2}-1} \text{ Hz}$
 - (c.) ∞
 - (d.) 1 Hz
47. A 5-point sequence $x[n]$ is given as
 $x[-3]=1, x[-2]=1, x[-1]=0, x[0]=5, x[1]=1$.
- Let $X(e^{j\omega})$ denote the discrete-time Fourier transform of $x[n]$. The value of $\int_{-\pi}^{\pi} X(e^{j\omega}) d\omega$ is
- (a.) 5
 - (b.) 10π
 - (c.) 16π
 - (d.) $5 + j10\pi$
48. The z-transform $X[z]$ of a sequence $x[n]$ is given by $X[z] = \frac{0.5}{1-2z^{-1}}$. If it is given that the region of convergence of $X[z]$ includes the unit circle. The value of $x[0]$ is
- (a.) -0.5
 - (b.) 0
 - (c.) 0.25
 - (d.) 0.5

49. The frequency response of a linear, time-invariant system is given by $H(f) = \frac{5}{1 + j10\pi f}$. The step response of the system is

(a.) $5(1 - e^{-5t})u(t)$

(b.) $5\left(1 - e^{-\frac{t}{5}}\right)u(t)$

(c.) $\frac{1}{5}(1 - e^{-5t})u(t)$

(d.) $\frac{1}{5}\left(1 - e^{-\frac{t}{5}}\right)u(t)$

50. A control system with a PD controller is shown in the figure. If the velocity error constant $K_v = 1000$ and the damping ratio $\xi = 0.5$, then the values of K_p and K_D



(a.) $K_p = 100, K_D = 0.09$

(b.) $K_p = 100, K_D = 0.9$

(c.) $K_p = 10, K_D = 0.09$

(d.) $K_p = 10, K_D = 0.9$

51. The transfer function of a plant is $T(s) = \frac{5}{(s+5)(s^2+s+1)}$. The second-order approximation of $T(s)$ using dominant pole concept is

(a.) $\frac{1}{(s+5)(s+1)}$

(b.) $\frac{5}{(s+5)(s+1)}$

(c.) $\frac{5}{s^2+s+1}$

(d.) $\frac{1}{s^2+s+1}$

52. The open-loop transfer function of a plant is given as $G(s) = \frac{1}{s^2 - 1}$. If the plant is operated in a unity feedback configuration, the lead compensator that can stabilize this control system is

(a.) $\frac{10(s-1)}{s+2}$

(b.) $\frac{10(s+4)}{s+2}$

(c.) $\frac{10(s+2)}{s+10}$

(d.) $\frac{2(s+2)}{s+10}$

53. A unity feedback control system has an open-loop transfer function

$$G(s) = \frac{K}{s(s^2 + 7s + 12)}. \text{ The gain } K \text{ for which } s = -1 + j1 \text{ will lie on the root locus of this system is}$$

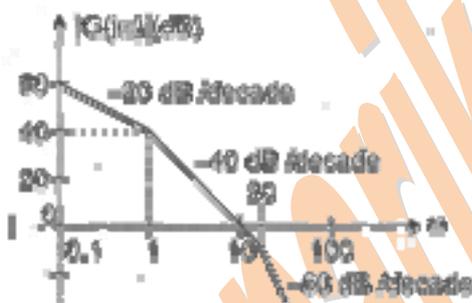
(a.) 4

(b.) 5.5

(c.) 6.5

(d.) 10

54. The asymptotic Bode plot of a transfer function is as shown in the figure. The transfer function $G(s)$ corresponding to this Bode plot is



(a.) $\frac{1}{(s+1)(s+20)}$

(b.) $\frac{1}{s(s+1)(s+20)}$

(c.) $\frac{100}{s(s+1)(s+20)}$

(d.) $\frac{100}{s(s+1)(s+0.05s)}$

55. The state space representation of a separately excited DC servo motor dynamics is given as

$$\begin{bmatrix} \frac{d\omega}{dt} \\ \frac{di_a}{dt} \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ -1 & -10 \end{bmatrix} \begin{bmatrix} \omega \\ i_a \end{bmatrix} + \begin{bmatrix} 0 \\ 10 \end{bmatrix} u$$

where ω is the speed of the motor, i_a is the armature current and u is the armature voltage. The transfer function $\frac{\omega(s)}{U(s)}$ of the motor is

(a.) $\frac{10}{s^2 + 11s + 11}$

(b.) $\frac{1}{s^2 + 11s + 11}$

(c.) $\frac{10s + 10}{s^2 + 11s + 11}$

(d.) $\frac{1}{s^2 + s + 1}$

Statement for Linked Answer

Questions 56 & 57:

Consider a linear system whose state space representation is $\dot{x}(t) = Ax(t)$. If the initial state vector of the system is $x(0) = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$, then the system response is $x(t) = \begin{bmatrix} e^{-2t} \\ -2e^{-2t} \end{bmatrix}$. If the initial state vector of the system changes to $x(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$, then this system response becomes $x(t) = \begin{bmatrix} e^{-t} \\ -t^{-t} \end{bmatrix}$.

56. The eigenvalue and eigenvector pairs (λ_i, v_i) for the system are

(a.) $\left(-1, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)$ and $\left(-2, \begin{bmatrix} 1 \\ -2 \end{bmatrix}\right)$

(b.) $\left(-2, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)$ and $\left(-1, \begin{bmatrix} 1 \\ -2 \end{bmatrix}\right)$

(c.) $\left(-1, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)$ and $\left(-2, \begin{bmatrix} 1 \\ -2 \end{bmatrix}\right)$

(d.) $\left(-2, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)$ and $\left(-1, \begin{bmatrix} 1 \\ -2 \end{bmatrix}\right)$

57. The system matrix A is

(a.) $\begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix}$

(b.) $\begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$

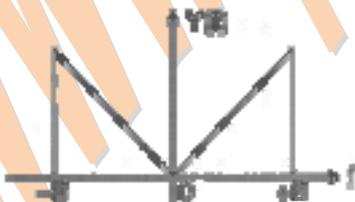
(c.) $\begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix}$

(d.) $\begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$

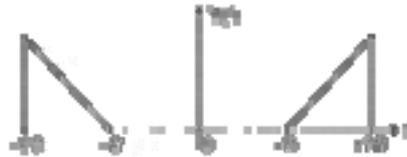
58. A Hilbert transformer is a
- non-linear system
 - non-causal system
 - time-varying system
 - low-pass system
59. In delta modulation, the slope overload distortion can be reduced by
- decreasing the step size
 - decreasing the granular noise
 - decreasing the sampling rate
 - increasing the step size
60. The raised cosine pulse $p(t)$ is used for zero ISI in digital communications. The expression for $p(t)$ with unity roll-off factor is given by $p(t) = \frac{\sin 4\pi Wt}{4\pi Wt(1-16W^2t^2)}$. The value of $p(t)$ at $t = \frac{1}{4W}$ is
- 0.5
 - 0
 - 0.5
 - ∞
61. In the following scheme, if the spectrum $M(f)$ of $m(t)$ is as shown, then the spectrum $Y(f)$ of $y(t)$ will be



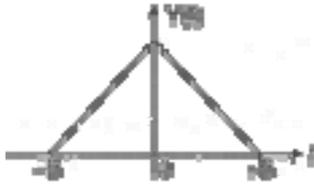
(a.)



(b.)



(c.)



(d.)

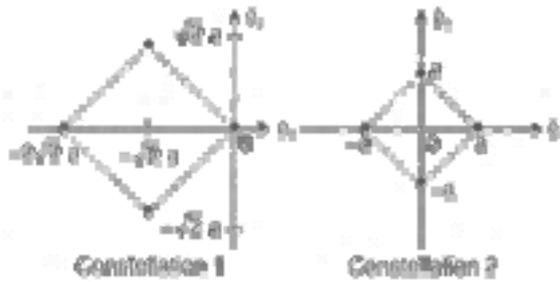


62. During transmission over a certain binary communication channel, bit errors occur independently with probability p . The probability of AT MOST one bit in error in a block of n bits is given by
- p^n
 - $1 - p^n$
 - $np(1 - p)^{n-1} + (1 - p)^n$
 - $1 - (1 - p)^n$
63. In a GSM system, 8 channels can co-exist in 200 kHz bandwidth using TDMA. A GSM based cellular operator is allocated 5 MHz bandwidth. Assuming a frequency reuse factor of $\frac{1}{5}$ i.e. a five-cell repeat pattern, the maximum number of simultaneous channels that can exist in one cell is
- 200
 - 40
 - 25
 - 5
64. In a Direct Sequence CDMA system the chip rate is 1.2288×10^6 chips per second, If the processing gain is desired to be AT LEAST 100, the data rate
- must be less than or equal to 12.288×10^3 bits per sec
 - must be greater than 12.288×10^3 bits per sec
 - must be exactly equal to 12.288×10^3 bits per sec
 - can take any value less than 122.88×10^3 bits per sec

Common Data for Questions 65 & 66:

Two 4-ary signal constellations are shown. It is given that ϕ_1 and ϕ_2 constitute an orthonormal basis for the two constellations. Assume that the four symbols in both the constellations are equiprobable.

Let $N_0/2$ denote the power spectral density of white Gaussian noise.

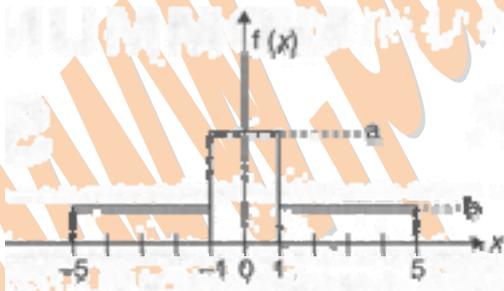


65. The ratio of the average energy of Constellation 1 to the average energy of Constellation 2 is
- $4a^2$
 - 4
 - 2
 - 8
66. If these constellations are used for digital communications over an A WGN channel, then which of the following statements is true?
- Probability of symbol error for Constellation 1 is lower
 - Probability of symbol error for Constellation 1 is higher
 - Probability of symbol error is equal for both the constellations
 - The value of N_0 will determine which of the two constellations has a lower probability of symbol error

Statement for Linked Answer

Questions 67 & 68:

An input to a 6-level quantizer has the probability density function $f(x)$ as shown in the figure. Decision boundaries of the quantizer are chosen so as to maximize the entropy of the quantizer output. It is given that 3 consecutive decision boundaries are '-1', '0' and '1'



67. The values of a and b are
- $a = 1/6$ and $b = 1/12$
 - $a = 1/5$ and $b = 3/40$
 - $a = 1/4$ and $b = 1/16$

(d.) $a = 1/3$ and $b = 1/24$

68. Assuming that the reconstruction levels of the quantizer are the mid-points of the decision boundaries, the ratio of signal power to quantization noise power is

(a.) $\frac{152}{9}$

(b.) $\frac{64}{3}$

(c.) $\frac{76}{3}$

(d.) 28

69. An air-filled rectangular waveguide has inner dimensions of $3 \text{ cm} \times 2 \text{ cm}$. The wave impedance of the TE_{20} mode of propagation in the waveguide at a frequency of 30 GHz is (free space impedance $\eta_0 = 377 \Omega$)

(a.) 308Ω

(b.) 355Ω

(c.) 400Ω

(d.) 461Ω

70. The \vec{H} field (in A/m) of a plane wave propagating in free space is given by

$$\vec{H} = \hat{x} \frac{5\sqrt{3}}{\eta_0} \cos(\omega t - \beta z) + \hat{y} \frac{5}{\eta_0} \sin\left(\omega t - \beta z + \frac{\pi}{2}\right)$$

The time average power flow density in Watts is

(a.) $\frac{\eta_0}{100}$

(b.) $\frac{100}{\eta_0}$

(c.) $50\eta_0^2$

(d.) $\frac{50}{\eta_0}$

71. The \vec{E} field in a rectangular waveguide of inner dimensions $a \times b$ is given by

$$\vec{E} = \frac{\omega\mu}{h^2} \left(\frac{\pi}{a}\right) H_0 \sin\left(\frac{2\pi x}{a}\right) \sin(\omega t - \beta z) \hat{y}$$

where H_0 is a constant, and a and b are the dimensions along the x -axis and the y -axis respectively. The mode of propagation in the waveguide is

(a.) TE_{20}

(b.) TM_{11}

(c.) TM_{20}

(d.) TE_{10}

72. A load of 50Ω is connected in shunt in a 2-wire transmission line of $Z_0 = 50 \Omega$ as shown in the figure. The 2-port scattering parameter matrix (S-matrix) of the shunt element is



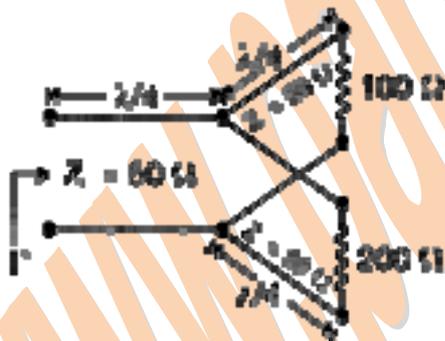
(a.)
$$\begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$

(b.)
$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

(c.)
$$\begin{bmatrix} -\frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & -\frac{1}{3} \end{bmatrix}$$

(d.)
$$\begin{bmatrix} \frac{1}{4} & -\frac{3}{4} \\ -\frac{3}{4} & \frac{1}{4} \end{bmatrix}$$

73. The parallel branches of a 2-wire transmission line are terminated in 100Ω and 200Ω resistors as shown in the figure. The characteristic impedance of the line is $Z_0 = 50 \Omega$ and each section has a length of $\frac{\lambda}{4}$. The voltage reflection coefficient Γ at the input is



(a.) $-j\frac{7}{5}$

(b.) $\frac{-5}{7}$

(c.) $j\frac{5}{7}$

(d.) $\frac{5}{7}$

74. A $\frac{\lambda}{2}$ dipole is kept horizontally at a height of $\frac{\lambda_0}{2}$ above a perfectly conducting infinite ground plane. The radiation pattern in the plane of the dipole (\vec{E} plane) looks approximately is

(a.)



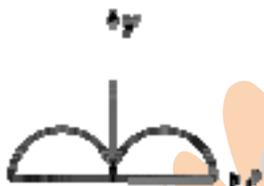
(b.)



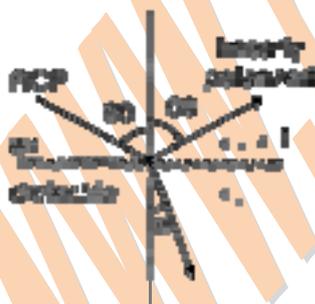
(c.)



(d.)



75. A right circularly polarized (RCP) plane wave is incident at an angle of 60° to the normal, on an air-dielectric interface. If the reflected wave is linearly polarized, the relative dielectric constant ϵ_2 is

(a.) $\sqrt{2}$ (b.) $\sqrt{3}$

(c.) 2

(d.) 3

76. An 8255 chip is interfaced to an 8085 microprocessor system as an I/O mapped I/O as shown in the figure. The address lines A_0 and A_1 of the 8085 are used by the 8255 chip to decode internally its three ports and the Control register. The address lines A_3 to A_7 as well as the IO/\overline{M} signal are used for address decoding. The range of addresses for which the 8255 chip would get selected is



- (a.) F8H — FBH
 (b.) F8H — FCH
 (c.) F8H — FFH
 (d.) FOH — F7H

Statement for Linked Answer

Questions 76 & 77:

An 8085 assembly language program is given below.

Line 1: MVI A, B5H
 2: MVI B, 0EH
 3: XRI 69H
 4: ADDB
 5: ANI 9BH
 6: CPI 9FH
 7: STA3010H
 8: HLT

77. The contents of the accumulator just after execution of the ADD instruction in line 4 will be
 (a.) C3H
 (b.) EAH
 (c.) DCH
 (d.) 69H
78. After execution of line 7 of the program, the status of the CY and Z flags will be
 (a.) CY = 0, Z = 0
 (b.) CY = 0, Z = 1
 (c.) CY = 1, Z = 0
 (d.) CY = 1, Z = 1

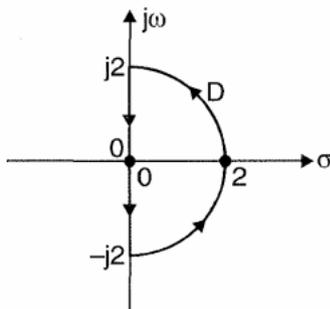
79. It is given that X_1, X_2, \dots, X_M are M non-zero, orthogonal vectors. The dimension of the vector space spanned by the $2M$ vectors $X_1, X_2, \dots, X_M, -X_1, -X_2, \dots, -X_M$, is
- (a.) $2M$
(b.) $M + 1$
(c.) M
(d.) dependent on the choice of X_1, X_2, \dots, X_M
80. Consider the function $f(x) = x^2 - x - 2$. The maximum value of $f(x)$ in the closed interval $[-4, 4]$ is
- (a.) 18
(b.) 10
(c.) - 2.25
(d.) indeterminate
81. An examination consists of two papers, Paper 1 and Paper 2. The probability of failing in Paper 1 is 0.3 and that in Paper 2 is 0.2. Given that a student has failed in Paper 2, the probability of failing in Paper 1 is 0.6. The probability of a student failing in both the papers is
- (a.) 0.5
(b.) 0.18
(c.) 0.12
(d.) 0.06
82. The solution of the differential equation $k^2 \frac{d^2 y}{dx^2} = y - y_2$ under the boundary conditions
- (i) $y = y_1$ at $x = 0$ and
(ii) $y = y_2$ at $x = \infty$, where k, y_1 and y_2 are constants, is
- (a.) $y = (y_1 - y_2) \exp(-x/k^2) + y_2$
(b.) $y = (y_2 - y_1) \exp(-x/k) + y_1$
(c.) $y = (y_1 - y_2) \sinh(x/k) + y_1$
(d.) $y = (y_1 - y_2) \exp(-x/k) + y_2$
83. The equation $x^3 - x^2 + 4x - 4 = 0$ is to be solved using the Newton-Raphson method. If $x = 2$ is taken as the initial approximation of the solution, then the next approximation using this method will be
- (a.) $\frac{2}{3}$
(b.) $\frac{4}{3}$
(c.) 1
(d.) $\frac{3}{2}$

84. Three functions $f_1(t)$, $f_2(t)$ and $f_3(t)$, which are zero outside the interval $[0, T]$, are shown in the figure. Which of the following statements is correct?



- (a.) $f_1(t)$ and $f_2(t)$ are orthogonal
 (b.) $f_1(t)$ and $f_3(t)$ are orthogonal
 (c.) $f_2(t)$ and $f_3(t)$ are orthogonal
 (d.) $f_1(t)$ and $f_2(t)$ are orthonormal
85. If the semi-circular contour D of radius 2 is as shown in the figure, then the value of the integral

$$\oint_D \frac{1}{(s^2 - 1)} ds \text{ is}$$



- (a.) $j\pi$
 (b.) $j\pi$
 (c.) $-j\pi$
 (d.) π