

Roll No.

Total No. of Questions : 09]

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Paper ID [A0310]

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B.Tech. (Sem. - 4th)

LINEAR CONTROL SYSTEMS (IC - 204)

Time : 03 Hours

Maximum Marks : 60

Instruction to Candidates:

- 1) Section - A is **Compulsory**.
- 2) Attempt any **Four** questions from Section - B.
- 3) Attempt any **Two** questions from Section - C.

Section - A

Q1)

(10 x 2 = 20)

- a) What is meant by Continuous and Discrete data systems?
- b) State significance and four properties of transfer function.
- c) Give advantages and disadvantages of block diagram reduction technique.
- d) Define rise time and delay time for a second order system.
- e) State Routh stability criteria and give its significance.
- f) What is meant by overdamped and underdamped system?
- g) Define Critically and Conditionally stable system.
- h) What do you mean by bounded input, bounded output stability of a system?
- i) Give advantages and limitations of Nyquist method.
- j) What is the effect of lag-lead compensator?

Section - B

(4 x 5 = 20)

- Q2) With the help of suitable example differentiate between
- Time variant and Time invariant systems.
 - Open and Closed loop systems.
 - Linear and Non-linear systems.
- Q3) Draw the heat transfer system and obtain its transfer function.
- Q4) State how steady state error of a control system is determined? How it can be reduced?
- Q5) Determine the stability of a system with characteristic equation.
- $$S^5 + 4S^4 + 2S^3 + 8S^2 + S + 4 = 0$$
- Q6) Compare the characteristics of three types of compensators.

Section - C

(2 x 10 = 20)

- Q7) What information can you obtain from the root locus? Explain the method of calculating the breakaway points. Draw the root locus plot for a system with

$$G(s) H(s) = \frac{k}{s(s^2 + 4s + 10)}$$

Determine angles of departure and the approximate positions of closed loop poles for $k = 10$.

- Q8) State the advantages of Bode plots. Determine the value of K in the transfer function given below such the
- The gain margin is 20 dB
 - The phase margin is 30°

$$G(j\omega) H(j\omega) = \frac{k}{j\omega(j0.1\omega + 1)(j0.05\omega + 1)}$$

- Q9) Sketch the Nyquist plot for system with

$$G(s) H(s) = \frac{(1 + 0.5s)}{s^2(1 + 0.1s)(1 + 0.02s)}$$

Comment on the stability.

