## Diplete - ET (NEW SCHEME) - Code: DE65

Subject: CONTROL ENGINEERING

**Time: 3 Hours** 

## **DECEMBER 2010**

Max. Marks: 100

NOTE: There are 9 Questions in all.

- Question 1 is compulsory and carries 20 marks. Answer to Q.1 must be written in the space provided for it in the answer book supplied and nowhere else.
- The answer sheet for the Q.1 will be collected by the invigilator after half an hour of the commencement of the examination.
- Out of the remaining EIGHT Questions answer any FIVE Questions. Each question carries 16 marks.
- Any required data not explicitly given, may be suitably assumed and stated.

## Q.1 Choose the correct or the best alternative in the following:

 $(2\times10)$ 

- a. The impulse response of a linear system is the output when the input x(t) is
  - $(\mathbf{A}) \mathbf{r}(\mathbf{t})$

(B)  $\delta(t)$ 

(C) u(t)

- **(D)** None of the above
- b. The initial value of the function f(t) whose Laplace transform is  $F(s) = \frac{4s}{s^3 + 2s^2 + 9s + 6}$ 
  - (A) 0

**(B)** 4

**(C)** 0.33

- **(D)** 0.166
- c. System is said to be stable if
  - (A) Bounded input, the output is unbounded.
  - **(B)** Bounded input, the output is bounded.
  - (C) Unbounded input, the output is bounded.
  - **(D)** Unbounded input, the output is unbounded.
- d. If  $G = \frac{4}{s(s+3)}$  and  $H = \frac{1}{s}$  then the system is
  - **(A)** Type 0

**(B)** Type 1

**(C)** Type 2

- **(D)** Type -1
- e. Let  $Y(s) = \frac{s^2 + s 1}{s^3 + 7s^2 + 14s + 8}$  the poles are at
  - (A) s = -1, -3, 2

**(B)** s = -2.3, -4

(C) s = -3.4.8

**(D)** s = -1, -2, -4

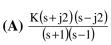
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- f. The acceleration error is finite in case
  - **(A)** Type 3

**(B)** Type 2

**(C)** Type 1

- **(D)** Type 0
- g. In root locus at breakaway point which one of the condition is satisfied
  - (A) Two are more branches of the root locus depart or arrive.
  - (B) Asymptotes are meeting at that point.
  - (C) Point at which rootlocus intersect with  $j\omega$  axis.
  - **(D)** None of the above.
- h. The root locus of a certain control system shown in Fig.1. The open loop transfer function of the system is





(C) 
$$\frac{K(s+2)}{(s+1-j2)(s+1+j2)}$$

**(D)** 
$$\frac{K(s+2)}{(s+1+j2)(s-1-j2)}$$

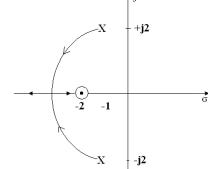


Fig.1

- i. Bode plot is plot of
  - (A) Magnitude plot
  - (B) Phase plot
  - (C) Both the magnitude and phase plot
  - (D) Neither magnitude nor phase plot
- j. In Nyquist stability criterion if N = 1 and P = 0 then the closed system is
  - (A) stable.

- (B) unstable.
- **(C)** critically stable.
- **(D)** None of the above.

## Answer any FIVE Questions out of EIGHT Questions. Each question carries 16 marks.

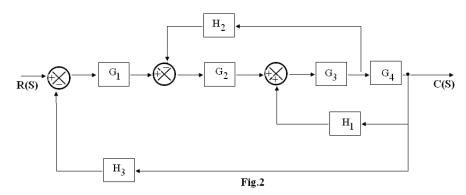
**Q.2** a. Define control system. Write the characteristics of feedback control system.

(6)

- b. Draw the general block diagram of a feedback control system and explain. (6)
- c. Give an example to both open loop and closed loop control system. (4)

Q.3 a. Find the free response of 
$$\frac{d^3y}{dt^3} + 6\frac{d^2y}{dt^2} + 11\frac{dy}{dt} + 6y = 0$$
 with the initial conditions  $y(0) = -1$ ,  $\frac{dy}{dt}\Big|_{t=0} = \frac{d^2y}{dt^2}\Big|_{t=0} = 0$ . (8)

- b. Find the partial fraction expansion of the function  $F(s) = \frac{10}{(s+4)(s+2)^2}$  and hence find the inverse Laplace transform. (8)
- Q.4 a. The characteristic equation of a system is  $s^4 + s^3 + 2s^2 + 9s + 5 = 0$ . Determine the number of roots in the right half S-plane use RH criterion. (8)
  - b. Explain the following block-diagram transformation theorems with proper diagrams. (8)
    - (i) Moving a summing point behind a block.
    - (ii) Moving a take off point ahead of a block.
- Q.5 a. Explain Mason's gain formula. (5)
  - b. For the block diagram shown in Fig.2, draw the signal flow graph. Also find the transfer function. (11)



- Q.6 a. Find the error constants and steady state error for the unity feedback system when the input is ramp if  $G(s) = \frac{100}{s^2(s+2)(s+5)}$ . (8)
  - b. Explain gain margin and phase margin? (8)
- Q.7 a. Explain Nyquist stability criterion. (6)
  - b. Given  $GH = \frac{12}{s(s+1)(s+2)}$ . Draw the polar plot and hence determine if system is stable. Calculate gain margin. (10)

- Q.8 a. Explain the angle and magnitude conditions of root loci. (4)
  - b. Construct the root locus for  $GH = \frac{K}{s(s+1)(s+2)}$  (12)
- Q.9 Draw the Bode diagrams for the both magnitude and phase with open loop transfer function as  $GH(s) = \frac{20(0.2s+1)}{s(0.5s+1)}$ . Also find gain margin and phase margin. (16)