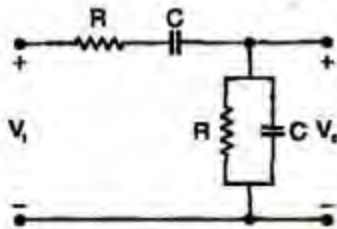


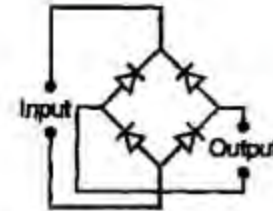
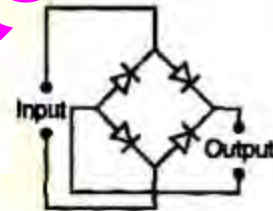
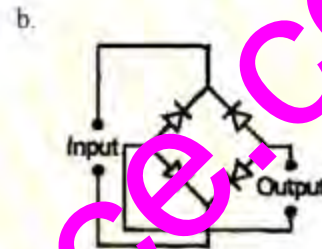
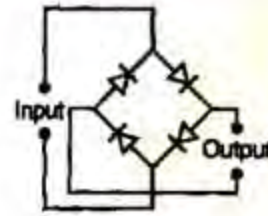
ELECTRONICS & COMMUNICATION ENGINEERING

ONE MARKS QUESTIONS

1. An independent voltage source in series with an impedance $Z_s = R_s + jX_s$ delivers a maximum average power to a load impedance Z_L when
- $Z_L = R_s + jX_s$
 - $Z_L = R_s$
 - $Z_L = jX_s$
 - $Z_L = R_s - jX_s$
2. The RC circuit shown in the figure is



- a low-pass filter
 - a high-pass filter
 - a band-pass filter
 - a band-reject filter
3. The electron and hole concentrations in an intrinsic semiconductor are n_i per cm^3 at 300 K. Now, if acceptor impurities are introduced with a concentration of N_A per cm^3 (where $N_A \gg n_i$) the electron concentration per cm^3 (at 300 K) will be
- n_i
 - $n_i + N_A$
 - $N_A - n_i$
 - $\frac{n_i^2}{N_A}$
4. In a p-n junction diode under reverse bias, the magnitude of electric field is maximum
- at the edge of the depletion region on the p-side
 - at the edge of the depletion region on the n-side
 - at the p-n junction
 - at the centre of the depletion region on the n-side
5. The correct full wave rectifier circuit is
-



- -
 -
 -
6. In a trans-conductance amplifier, it is desirable to have
- a large input resistance and a large output resistance
 - a large input resistance and a small output resistance
 - a small input resistance and a large output resistance
 - a small input resistance and a small output resistance
7. $X = 01110$ and $Y = 11001$ are two 5-bit binary numbers represented in two's complement format. The sum of X and Y represented in two's complement format using 6 bits is
- 100111
 - 001000

- c. 000111
d. 101001
8. The Boolean function $Y = AB + CD$ is to be realized using only 2-input NAND gates. The minimum number of gates required is
a. 2
b. 3
c. 4
d. 5
9. If the Laplace transform of a signal $y(t)$ is $Y(s) = \frac{1}{s(s-1)}$, then its final value is
a. -1
b. 0
c. 1
d. Unbounded
10. If $R(\tau)$ is the autocorrelation function of a real, wide-sense stationary random process, then which of the following is NOT true?
a. $R(\tau) = R(-\tau)$
b. $|R(\tau)| \leq R(0)$
c. $R(\tau) = -R(-\tau)$
d. The mean square value of the process is $R(0)$
11. If $S(f)$ is the power spectral density of a real, wide-sense stationary random process, then which of the following is ALWAYS true?
a. $S(0) \geq S(f)$
b. $S(f) \geq 0$
c. $S(-f) = S(f)$
d. $\int_{-\infty}^{\infty} S(f) df = 0$
12. If the closed-loop transfer function of a control system is given as $T(s) = \frac{s-5}{(s+2)(s+3)}$, then it is
a. an unstable system
b. a minimum phase system
c. an uncontrollable system
d. a non-minimum phase system
13. If E denotes expectation, the variance of a random variable X is given by
a. $E[X^2] - E^2[X]$
b. $E[X^2] + E^2[X]$

- c. $E[X^2]$
d. $E^2[X]$

14. A plane wave of wavelength λ is travelling in a direction making an angle 30° with positive x-axis and 90° with positive y-axis. The \vec{E} field of the plane wave can be represented as (E_0 is a constant)

a. $\vec{E} = y E_0 e^{j\left(\omega t - \frac{\sqrt{3}\pi}{\lambda}x - \frac{\pi}{\lambda}z\right)}$

b. $\vec{E} = y E_0 e^{j\left(\omega t - \frac{\pi}{\lambda}x - \frac{\sqrt{3}\pi}{\lambda}z\right)}$

c. $\vec{E} = y E_0 e^{j\left(\omega t - \frac{\sqrt{3}\pi}{\lambda}x - \frac{\pi}{\lambda}z\right)}$

d. $\vec{E} = y E_0 e^{j\left(\omega t - \frac{\pi}{\lambda}x - \frac{\sqrt{3}\pi}{\lambda}z\right)}$

15. If C is a closed curve enclosing a surface S , then the magnetic field intensity \vec{H} , the current density \vec{J} and the electric flux density \vec{D} are related by

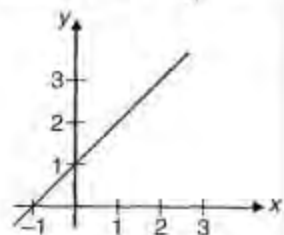
a. $\oint_C \vec{H} \cdot d\vec{s} = \iint_S \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{l}$

b. $\int_C \vec{H} \cdot d\vec{l} = \iint_S \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{s}$

c. $\iint_S \vec{H} \cdot d\vec{s} = \int_C \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{l}$

d. $\iint_C \vec{H} \cdot d\vec{l} = \iint_S \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{s}$

16. The following plot shows a function y which varies linearly with x . The value of the integral $I = \int_1^2 y dx$



- a. 1.0
b. 2.5
c. 4.0
d. 5.0

17. For $|x| \ll 1$, both $\ln(x)$ and e^x can be approximated as

- a. x
b. x^2

- c. $\frac{1}{x}$
 d. $\frac{1}{x^2}$
18. $\lim_{\theta \rightarrow 0} \frac{\sin(\theta/2)}{\theta}$ is
 a. 0.5
 b. 1
 c. 2
 d. Not defined
19. Which one of the following functions is strictly bounded?
 a. $\frac{1}{x^2}$
 b. e^x
 c. x^2
 d. e^{-x^2}
20. For the function e^x , the linear approximation around $x = 2$ is
 a. $(3-x)e^{-2}$
 b. $1-x$
 c. $[3+2\sqrt{2}-(1+\sqrt{2})x]e^{-2}$
 d. e^{-2}

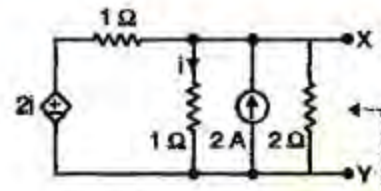
TWO MARKS QUESTIONS

21. Two series resonant filters are as shown in the figure. Let the 3 dB bandwidth of Filter 1 be B_1 and that of Filter 2 be B_2 .

The value of $\frac{B_1}{B_2}$ is

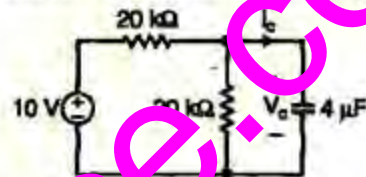


- a. 4
 b. 1
 c. $\frac{1}{2}$
 d. $\frac{1}{4}$
22. For the circuit shown in the figure, the Thevenin voltage and resistance looking into X-Y are



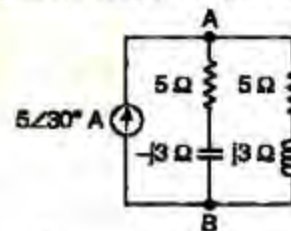
- a. 4/3V, 2Ω
 b. 4V, 2/3Ω
 c. 4/3 V, 2/3Ω
 d. 4 V, 2Ω

23. In the circuit shown, V_C is 0 volts at $t = 0$ sec. For $t > 0$, the capacitor current $i(t)$, where t is in seconds, is given by



- a. $0.50 \exp(-25t)$ mA
 b. $0.25 \exp(-25t)$ mA
 c. $0.50 \exp(-12.5t)$ mA
 d. $0.25 \exp(-6.25t)$ mA

24. In the AC network shown in the figure, the phasor voltage V_{AB} (in Volts) is



- a. 0
 b. $5\angle 30^\circ$
 c. $12.5\angle 30^\circ$
 d. $17\angle 30^\circ$

25. Group I lists four types of p-n junction diodes. Match each device in Group I with one of the options in Group II to indicate the bias condition of that device in its normal mode of operation.

Group I

- A. Zener Diode
 B. Solar cell
 C. LASER diode
 D. Avalanche Photodiode

Group II

1. Forward bias
 2. Reverse bias

Codes:

- | | A | B | C | D |
|----|---|---|---|---|
| a. | 1 | 2 | 1 | 2 |

- b. 2 1 1 2
 c. 2 2 2 1
 d. 2 1 2 2

26. Group I lists four different semiconductor devices. Match each device in Group I with its characteristic property in Group II.

Group I

- A. BJT
 B. MOS capacitor
 C. LASER diode
 D. JFET

Group II

1. Population inversion
 2. Pinch-off voltage
 3. Early effect
 4. Flat-band voltage

Codes:

- | | A | B | C | D |
|----|---|---|---|---|
| a. | 3 | 1 | 4 | 2 |
| b. | 1 | 4 | 3 | 2 |
| c. | 3 | 4 | 1 | 2 |
| d. | 3 | 2 | 1 | 4 |

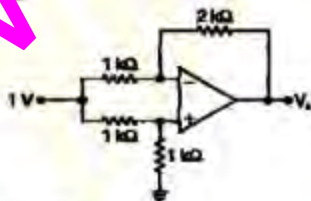
27. A p-n junction has a built-in potential of 0.8 V. The depletion layer width at a reverse bias of 1.2 V is 2 μm . For a reverse bias of 7.2 V, the depletion layer width will be

- a. 4 μm
 b. 4.9 μm
 c. 8 μm
 d. 12 μm

28. The DC current gain β_{DC} of a BJT is 50. Assuming that the emitter injection efficiency is 0.995, the base transport factor is

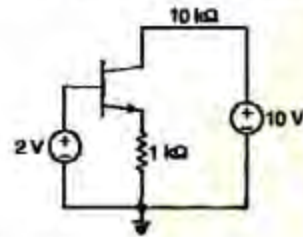
- a. 0.980
 b. 0.985
 c. 0.99
 d. 0.995

29. For the Op-Amp circuit shown in the figure, V_0 is



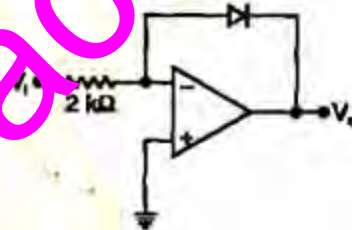
- a. -2V
 b. -1V
 c. -0.5V
 d. 0.5V

30. For the BJT circuit shown, assume that the β of the transistor is very large and $V_{BE} = 0.7\text{ V}$. The mode of operation of the BJT is



- a. cut-off
 b. saturation
 c. normal active
 d. reverse active

31. In the OP-Amp circuit shown, assume that the diode current follows the equation $I = I_s \exp(V/V_T)$. For $V_1 = 2\text{ V}$, $V_0 = V_{01}$, and for $V_1 = 4\text{ V}$, $V_0 = V_{02}$. The relationship between V_{01} and V_{02} is

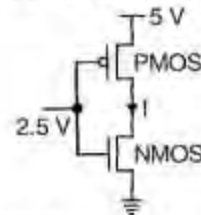


- a. $V_{02} = \sqrt{2} V_{01}$
 b. $V_{02} = e^2 V_{01}$
 c. $V_{02} = V_{01} \ln 2$
 d. $V_{01} - V_{02} = V_T \ln 2$

32. In the CMOS inverter circuit shown, if the trans-conductance parameters of the NMOS and PMOS transistors are $k_n = k_p = \mu C_{ox} \frac{W_n}{L_n} = \mu_p C_{ox} \frac{W_p}{L_p} = 40 \mu\text{A/V}^2$ and

$$\mu C_{ox} \frac{W_n}{L_n} = \mu_p C_{ox} \frac{W_p}{L_p} = 40 \mu\text{A/V}^2$$

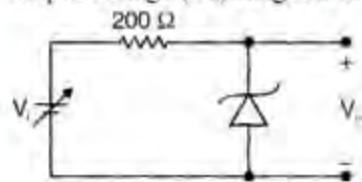
their threshold voltages are $V_{THn} = |V_{THp}| = 1\text{ V}$, the current I is



- a. 0 A
 b. 25 μA
 c. 45 μA
 d. 90 μA

33. For the Zener diode shown in the figure, the Zener voltage at knee is 7 V, the knee current is negligible and the Zener

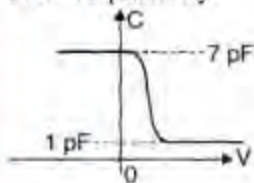
dynamic resistance is 10Ω . If the input voltage (V_i) range is from 10 to 16 V, the output voltage (V_o) ranges from



- 7.00 to 7.29V
- 7.14 to 7.29V
- 7.14 to 7.43V
- 7.29 to 7.43V

Common Data Questions 34, 35, 36:

The figure shows the high-frequency capacitance-voltage ($C-V$) characteristics of a Metal/SiO₂/silicon (MOS) capacitor having an area of 1×10 cm². Assume that the permittivities ($\epsilon_0\epsilon_r$) of silicon and SiO₂ are 1×10^{-12} F/cm and 3.5×10^{-13} F/cm respectively.



- The gate oxide thickness in the MOS capacitor is:
 - 50 nm
 - 143 nm
 - 350 nm
 - $1 \mu\text{m}$
- The maximum depletion layer width in silicon is:
 - $0.143 \mu\text{m}$
 - $0.857 \mu\text{m}$
 - $1 \mu\text{m}$
 - $1.43 \mu\text{m}$
- Consider the following statements about the $C-V$ characteristics plot:

S1: The MOS capacitor has as n-type substrate.

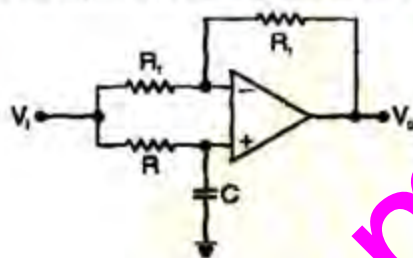
S2: If positive charges are introduced in the oxide, the $C-V$ plot will shift to the left.

Then which of the following is true?

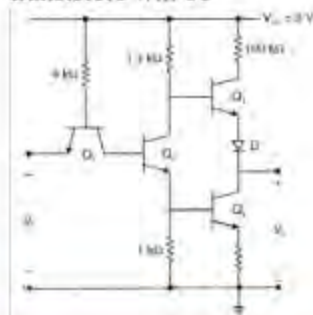
 - Both S1 and S2 are true
 - S1 is true and S2 is false
 - S1 is false and S2 is true
 - Both S1 and S2 are false

Statement for Linked Answer Questions 37 & 38:

Consider the Op-Amp circuit shown in the figure.

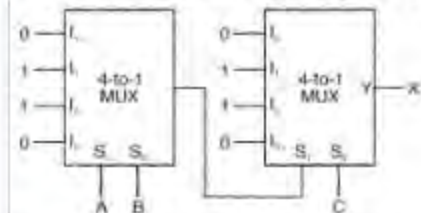


- The transfer function $V_o(s)/V_i(s)$ is
 - $\frac{1-sRC}{1+sRC}$
 - $\frac{1+sRC}{1-sRC}$
 - $\frac{1}{1-sRC}$
 - $\frac{1}{1+sRC}$
- If $V_i = V_1 \sin(\omega t)$ and $V_o = V_2 \sin(\omega t + \phi)$, then the minimum and maximum values of ϕ (in radians) are respectively. Consider the Op-Amp circuit shown in the figure.
 - $-\pi/2$ and $\pi/2$
 - 0 and $\pi/2$
 - $-\pi$ and 0
 - $-\pi/2$ and 0
- The Boolean expression $Y = \overline{A}BCD + \overline{A}BC\overline{D} + \overline{A}B\overline{C}D + \overline{A}B\overline{C}\overline{D} + \overline{A}B\overline{C}D + \overline{A}B\overline{C}\overline{D} + \overline{A}B\overline{C}D + \overline{A}B\overline{C}\overline{D}$ can be minimized to
 - $Y = \overline{A}BCD + \overline{A}BC + \overline{A}CD$
 - $Y = \overline{A}BCD + BC\overline{D} + \overline{A}BC\overline{D}$
 - $Y = \overline{A}BCD + \overline{B}CD + \overline{A}BC\overline{D}$
 - $Y = \overline{A}BCD + \overline{B}CD + \overline{A}BC\overline{D}$
- The circuit diagram of a standard TTL NOT gate is shown in the figure. When $V_i = 2.5$ V, the modes of operation of the transistors will be



- a. Q_1 : reverse active; Q_2 : normal active; Q_3 : saturation; Q_4 : cut-off
 b. Q_1 : reverse active; Q_2 : saturation; Q_3 : saturation; Q_4 : cut-off
 c. Q_1 : normal active; Q_2 : cut-off; Q_3 : cut-off; Q_4 : saturation
 d. Q_1 : saturation; Q_2 : saturation; Q_3 : saturation; Q_4 : normal active

41. In the following circuit, X is given by



- a. $X = A\bar{B}\bar{C} + \bar{A}B\bar{C} + \bar{A}\bar{B}C + ABC$
 b. $X = \bar{A}BC + A\bar{B}C + ABC + \bar{A}\bar{B}\bar{C}$
 c. $X = AB + BC + AC$
 d. $X = \bar{A}\bar{B} + \bar{B}\bar{C} + \bar{A}\bar{C}$
42. The following binary values were applied to the X and Y inputs of the NAND latch shown in the figure in the sequence indicated below:

$X = 0, Y = 1$;

$X = 0, Y = 0$;

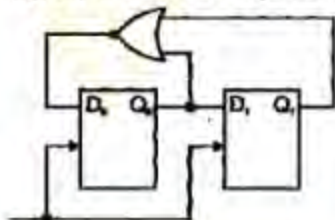
$X = 1, Y = 1$.

The corresponding stable P, Q outputs will be



- a. $P = 1, Q = 0$; $P = 1, Q = 0$; $P = 1, Q = 0$ or $P = 0, Q = 1$
 b. $P = 1, Q = 0$; $P = 0, Q = 1$ or $P = 0, Q = 1$ or $P = 0, Q = 1$
 c. $P = 1, Q = 0$; $P = 1, Q = 1$; $P = 1, Q = 0$ or $P = 0, Q = 1$
 d. $P = 1, Q = 0$; $P = 1, Q = 1$; $P = 1, Q = 1$

For the circuit shown, the counter state (Q_1Q_0) follows the sequence

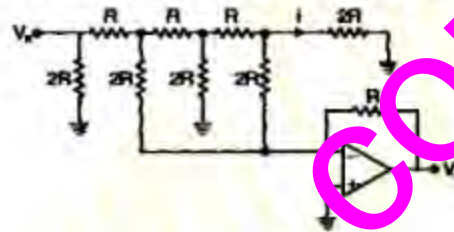


- a. 00,01,10,11,00...
 b. 00,01,10,00,01...
 c. 00, 01, 11,00,01...
 d. 00, 10, 11,00, 10...

Statement for Linked Answer

Questions 44 & 45:

In the Digital-to-Analog converter circuit shown in the figure below, $V_R = 10$ V and $R = 10$ k Ω .



44. The current i is
 a. 1.25 μ A
 b. 62.5 μ A
 c. 12.5 μ A
 d. 250 μ A
45. The voltage V_0 is
 a. -0.781 V
 b. -1.562 V
 c. -3.125 V
 d. -6.250 V
46. The 3-dB bandwidth of the low-pass signal $e'u(t)$, where $u(t)$ is the unit step function, is given by
 a. $\frac{1}{2\pi}$ Hz
 b. $\frac{1}{2\pi}\sqrt{\sqrt{2}-1}$ Hz
 c. ∞
 d. 1 Hz
47. A 5-point sequence $x[n]$ is given as $x[-3]=1, x[-2]=1, x[-1]=0, x[0]=5, x[1]=1$. Let $X(e^{j\omega})$ denote the discrete-time Fourier transform of $x[n]$. The value of $\int_{-\pi}^{\pi} X(e^{j\omega}) d\omega$ is
 a. 5
 b. 10π
 c. 16π
 d. $5 + j10\pi$

48. The z-transform $X[z]$ of a sequence $x[n]$ is given by $X[z] = \frac{0.5}{1-2z^{-1}}$. If it is given that the region of convergence of $X[z]$ includes the unit circle. The value of $x[0]$ is

- 0.5
- 0
- 0.25
- 0.5

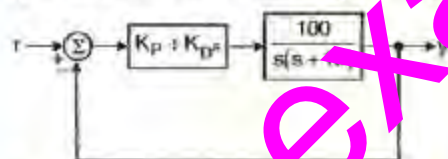
49. The frequency response of a linear, time-invariant system is given by

$$H(f) = \frac{5}{1+j10\pi f}$$

The step response of the system is

- $5(1 - e^{-5t})u(t)$
- $5\left(1 - e^{-\frac{t}{5}}\right)u(t)$
- $\frac{1}{5}(1 - e^{-5t})u(t)$
- $\frac{1}{5}\left(1 - e^{-\frac{t}{5}}\right)u(t)$

50. A control system with a PD controller is shown in the figure. If the velocity error constant $K_v = 1000$ and the damping ratio $\zeta = 0.5$, then the values of K_p and K_D are



- $K_p = 100, K_D = 0.09$
- $K_p = 100, K_D = 0.9$
- $K_p = 10, K_D = 0.09$
- $K_p = 0, K_D = 0.9$

51. The transfer function of a plant is

$$T(s) = \frac{5}{(s+5)(s^2+s+1)}$$

The second-order approximation of $T(s)$ using dominant pole concept is

- $\frac{1}{(s+5)(s+1)}$
- $\frac{5}{(s+5)(s+1)}$
- $\frac{5}{s^2+s+1}$

$$d. \frac{1}{s^2+s+1}$$

52. The open-loop transfer function of a plant is given as $G(s) = \frac{1}{s^2-1}$. If the plant is

operated in a unity feedback configuration, the lead compensator that can stabilize this control system is

- $\frac{10(s-1)}{s+2}$
- $\frac{10(s+4)}{s+2}$
- $\frac{10(s+2)}{s+10}$
- $\frac{2(s+2)}{s+10}$

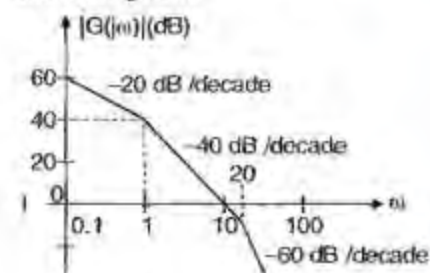
53. A unity feedback control system has an open-loop transfer function

$$G(s) = \frac{K}{s(s^2+7s+12)}$$

which $s = -1 + j1$ will lie on the root locus of this system is

- 4
- 5.5
- 6.5
- 10

54. The asymptotic Bode plot of a transfer function is shown in the figure. The transfer function $G(s)$ corresponding to this Bode plot is



- $\frac{1}{(s+1)(s+20)}$
- $\frac{1}{s(s+1)(s+20)}$
- $\frac{100}{s(s+1)(s+20)}$
- $\frac{100}{s(s+1)(s+0.05s)}$

55. The state space representation of a separately excited DC servo motor dynamics is given as

$$\begin{bmatrix} \frac{d\omega}{dt} \\ \frac{di_a}{dt} \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ -1 & -10 \end{bmatrix} \begin{bmatrix} \omega \\ i_a \end{bmatrix} + \begin{bmatrix} 0 \\ 10 \end{bmatrix} u$$

where ω is the speed of the motor, i_a is the armature current and u is the armature voltage. The transfer function $\frac{\omega(s)}{U(s)}$ of the

motor is

- $\frac{10}{s^2 + 11s + 11}$
- $\frac{1}{s^2 + 11s + 11}$
- $\frac{10s + 10}{s^2 + 11s + 11}$
- $\frac{1}{s^2 + s + 1}$

Statement for Linked Answer

Questions 56 & 57:

Consider a linear system whose state space representation is $\dot{x}(t) = Ax(t)$. If the initial state

vector of the system is $x(0) = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$, then the

system response is $x(t) = \begin{bmatrix} e^{-2t} \\ -2e^{-2t} \end{bmatrix}$. If the initial

state vector of the system changes to $x(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$,

then this system response becomes $x(t) = \begin{bmatrix} e^{-t} \\ -t e^{-t} \end{bmatrix}$.

56. The eigenvalue and eigenvector pairs (λ, v) for the system are

- $\left(-1, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)$ and $\left(-2, \begin{bmatrix} 1 \\ -2 \end{bmatrix}\right)$
- $\left(-2, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)$ and $\left(-1, \begin{bmatrix} 1 \\ -2 \end{bmatrix}\right)$
- $\left(-1, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)$ and $\left(-2, \begin{bmatrix} 1 \\ -2 \end{bmatrix}\right)$
- $\left(-2, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)$ and $\left(-1, \begin{bmatrix} 1 \\ -2 \end{bmatrix}\right)$

57. The system matrix A is

- $\begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix}$
- $\begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$
- $\begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix}$
- $\begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$

58. A Hubert transformer is a

- non-linear system
- non-causal system
- time-varying system
- low-pass system

59. In delta modulation, the slope overload distortion can be reduced by

- decreasing the step size
- decreasing the granular noise
- decreasing the sampling rate
- increasing the step size

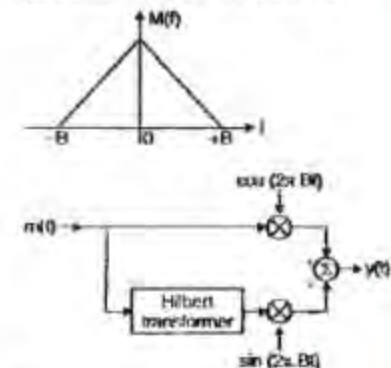
60. The raised cosine pulse $p(t)$ is used for zero ISI in digital communications. The expression for $p(t)$ with unity roll-off factor is given by

$$p(t) = \frac{\sin 4\pi Wt}{4\pi Wt(1-16W^2t^2)}$$

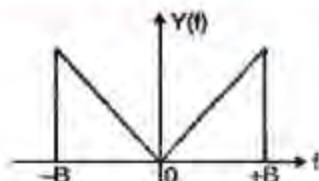
The value of $p(t)$ at $t = \frac{1}{4W}$ is

- 0.5
- 0
- 0.5
- ∞

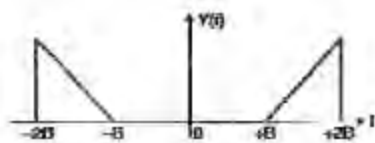
61. In the following scheme, if the spectrum $M(f)$ of $m(t)$ is as shown, then the spectrum $Y(f)$ of $y(t)$ will be



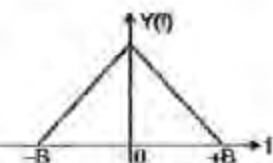
- a.



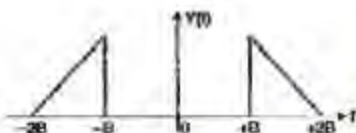
b.



c.



d.



62. During transmission over a certain binary communication channel, bit errors occur independently with probability p . The probability of AT MOST one bit in error in a block of n bits is given by

- p^n
- $1 - p^n$
- $np(1 - p)^{n-1} + (1 - p)^n$
- $1 - (1 - p)^n$

63. In a GSM system, 8 channels can co-exist in 200 kHz bandwidth using TDMA. A GSM based cellular operator is allocated 5 MHz bandwidth. Assuming a frequency reuse factor of $\frac{1}{5}$, i.e., a five-cell repeat pattern, the maximum number of simultaneous channels that can exist in one cell is

- 200
- 40
- 25
- 5

64. In a Direct Sequence CDMA system the chip rate is 1.2288×10^6 chips per second. If the processing gain is desired to be AT LEAST 100, the data rate

- must be less than or equal to 12.288×10^3 bits per sec

- must be greater than 12.288×10^3 bits per sec
- must be exactly equal to 12.288×10^3 bits per sec
- can take any value less than 122.88×10^3 bits per sec

Common Data for Questions 65 & 66:

Two 4-ary signal constellations are shown. It is given that ϕ_1 and ϕ_2 constitute an orthonormal basis for the two constellations. Assume that the four symbols in both the constellations are equiprobable.

Let $N_0/2$ denote the power spectral density of white Gaussian noise.



65. The ratio of the average energy of Constellation 1 to the average energy of Constellation 2 is

- $4a^2$
- 4
- 2
- 8

66. If these constellations are used for digital communications over an AWGN channel, then which of the following statements is true?

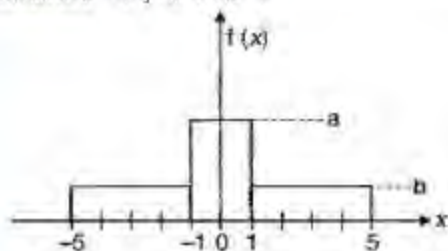
- Probability of symbol error for Constellation 1 is lower
- Probability of symbol error for Constellation 1 is higher
- Probability of symbol error is equal for both the constellations
- The value of N_0 will determine which of the two constellations has a lower probability of symbol error

Statement for Linked Answer

Questions 67 & 68:

An input to a 6-level quantizer has the probability density function $f(x)$ as shown in the figure. Decision boundaries of the quantizer are chosen so as to maximize the entropy of the quantizer

output. It is given that 3 consecutive decision boundaries are '-1', '0' and '1'



67. The values of a and b are
- $a = 1/6$ and $b = 1/12$
 - $a = 1/5$ and $b = 3/40$
 - $a = 1/4$ and $b = 1/16$
 - $a = 1/3$ and $b = 1/24$
68. Assuming that the reconstruction levels of the quantizer are the mid-points of the decision boundaries, the ratio of signal power to quantization noise power is

- $\frac{152}{9}$
- $\frac{64}{3}$
- $\frac{76}{3}$
- 28

69. An air-filled rectangular waveguide has inner dimensions of $3 \text{ cm} \times 2 \text{ cm}$. The wave impedance of the TE_{20} mode of propagation in the waveguide at a frequency of 30 GHz is (free space impedance $\eta_0 = 377 \Omega$)

- 308Ω
- 355Ω
- 400Ω
- 461Ω

70. The \vec{H} field (in Aim) of a plane wave propagating in free space is given by

$$\vec{H} = x \frac{\sqrt{3}}{\eta_0} \cos(\alpha x - \beta z) + y \frac{5}{\eta_0} \sin\left(\alpha x - \beta z + \frac{\pi}{2}\right)$$

The time average power flow density in Watts is

- $\frac{\eta_0}{100}$
- $\frac{100}{\eta_0}$
- $50\eta_0^2$

d. $\frac{50}{\eta_0}$

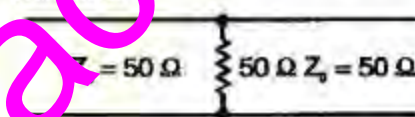
71. The \vec{E} field in a rectangular waveguide of inner dimensions $a \times b$ is given by

$$\vec{E} = \frac{\omega\mu}{h^2} \left(\frac{\pi}{a}\right) H_0 \sin\left(\frac{2\pi x}{a}\right) \sin(\alpha t - \beta z) \hat{y}$$

where H_0 is a constant, and a and b are the dimensions along the x -axis and the y -axis respectively. The mode of propagation in the waveguide is

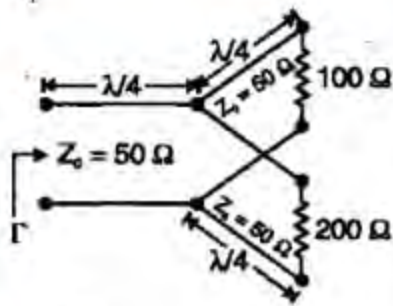
- TE_{20}
- TM_{11}
- TM_{20}
- TE_{10}

72. A load of 50Ω is connected in shunt in a 2-wire transmission line of $Z_0 = 50 \Omega$ as shown in the figure. The 2-port scattering parameter matrix (S-matrix) of the shunt element is







- $\begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$
- $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$
- $\begin{bmatrix} \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & -\frac{1}{3} \end{bmatrix}$
- $\begin{bmatrix} \frac{1}{4} & -\frac{3}{4} \\ -\frac{3}{4} & \frac{1}{4} \end{bmatrix}$

73. The parallel branches of a 2-wire transmission line are terminated in 100Ω and 200Ω resistors as shown in the figure. The characteristic impedance of the line is $Z_0 = 50 \Omega$ and each section has a length of $\frac{\lambda}{4}$. The voltage reflection coefficient Γ at the input is



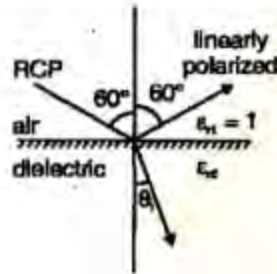
- a. $-j\frac{7}{5}$
- b. $\frac{-5}{7}$
- c. $j\frac{5}{7}$
- d. $\frac{5}{7}$

74. A $\frac{\lambda}{2}$ dipole is kept horizontally at a height of $\frac{\lambda_0}{2}$ above a perfectly conducting infinite ground plane. The radiation pattern in the plane of the dipole (\vec{E} plane) looks approximately is

- a. 
- b. 
- c. 
- d. 

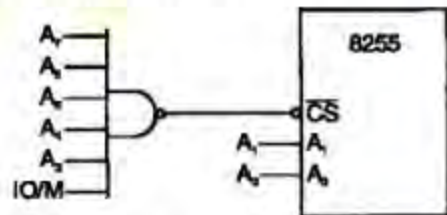
75. A right circularly polarized (RCP) plane wave is incident at an angle of 60° to the

normal, on an air-dielectric interface. If the reflected wave is linearly polarized, the relative dielectric constant ϵ_{r2} is



- a. $\sqrt{2}$
- b. $\sqrt{3}$
- c. 2
- d. 3

76. An 8255 PPI is interfaced to an 8085 microprocessor system as an I/O mapped I/O as shown in the figure. The address lines A_0 and A_1 of the 8085 are used by the 8255 chip to decode internally its three ports and the Control register. The address lines A_3 to A_7 as well as the $\overline{IO/\overline{M}}$ signal are used for address decoding. The range of addresses for which the 8255 chip would get selected is



- a. F8H — FBH
- b. F8H — FCH
- c. F8H — FFH
- d. FOH — F7H

Statement for Linked Answer

Questions 76 & 77:

An 8085 assembly language program is given below.

- Line 1: MVLA, B5H
 2: MVI B, 0EH
 3: XRI 69H
 4: ADDB
 5: ANI 9BH
 6: CPI 9FH
 7: STA3010H
 8: HLT

77. The contents of the accumulator just after execution of the ADD instruction in line 4 will be

- C3H
- EAH
- DCH
- 69H

78. After execution of line 7 of the program, the status of the CY and Z flags will be

- CY = 0, Z = 0
- CY = 0, Z = 1
- CY = 1, Z = 0
- CY = 1, Z = 1

79. It is given that X_1, X_2, \dots, X_M are M non-zero, orthogonal vectors. The dimension of the vector space spanned by the $2M$ vectors $X_1, X_2, \dots, X_M, -X_1, -X_2, \dots, -X_M$ is

- $2M$
- $M + 1$
- M
- dependent on the choice of X_1, X_2, \dots, X_M

80. Consider the function $f(x) = x^2 - x - 2$. The maximum value of $f(x)$ in the closed interval $[-4, 4]$ is

- 18
- 10
- 2.25
- indeterminate

81. An examination consists of two papers, Paper 1 and Paper 2. The probability of failing in Paper 1 is 0.4 and that in Paper 2 is 0.2. Given that a student has failed in Paper 2, the probability of failing in Paper 1 is 0.6. The probability of a student failing in both the papers is

- 0.5
- 0.8
- 0.2
- 0.6

82. The solution of the differential equation $k^2 \frac{d^2 y}{dx^2} = y - y_2$ under the boundary conditions

- $y = y_1$ at $x = 0$ and
- $y = y_2$ at $x = \infty$, where k, y_1 and y_2 are constants, is

- $y = (y_1 - y_2) \exp(-x/k^2) + y_2$
- $y = (y_2 - y_1) \exp(-x/k) + y_1$

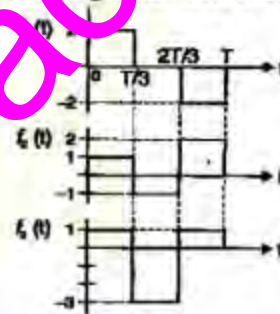
c. $y = (y_1 - y_2) \sinh(x/k) + y_1$

d. $y = (y_1 - y_2) \exp(-x/k) + y_2$

83. The equation $x^3 - x^2 + 4x - 4 = 0$ is to be solved using the Newton-Raphson method. If $x = 2$ is taken as the initial approximation of the solution, then the next approximation using this method will be

- $\frac{2}{3}$
- $\frac{4}{3}$
- 1
- $\frac{3}{2}$

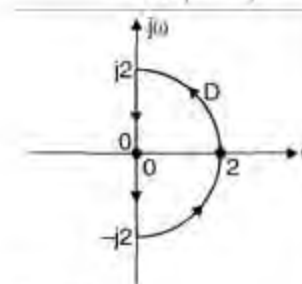
84. Three functions $f_1(t)$, $f_2(t)$ and $f_3(t)$, which are zero outside the interval $[0, T]$, are shown in the figure. Which of the following statements is correct?



- $f_1(t)$ and $f_2(t)$ are orthogonal
- $f_1(t)$ and $f_3(t)$ are orthogonal
- $f_2(t)$ and $f_3(t)$ are orthogonal
- $f_1(t)$ and $f_2(t)$ are orthonormal

85. If the semi-circular contour D of radius 2 is as shown in the figure, then the value of

the integral $\int_D \frac{1}{(s^2 - 1)} ds$ is



- $j\pi$
- $j\pi$
- $-j\pi$
- π