S.E. (Instrumentation) (I Sem.) EXAMINATION, 2010 PRINCIPLES OF SENSORS AND TRANSDUCERS (2008 COURSE)

Time: Three Hours

Maximum Marks: 100

- N.B. :- (i) Answer three questions from Section I and three questions from Section II.
 - Answers to the two Sections should be written in separate (ii)answer-books.
 - Neat diagrams must be drawn wherever necessary. (iii)
 - (iv) Use of logarithmic tables, slide rule, Mollier charts, electronic pocket calculator and steam tables is allowed.

- State the objectives of Engineering measurements. Define (a) [6] measurement.
 - Distinguish between : (b)
 - (i) Acturacy and Precision
 - ii) Threshold and Resolution. [6]
 - st the types of errors in measurement. Give their causes and state the remedies. [6]

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2.	(a)	Define calibration. Distinguish between active transducers and
	1 01	passive transducers. [6]
	(b)	State and explain any three desirable static and dynamic
no		characteristics of an instrument. [6]
S /	(c)	Classify transducers based on different transduction
		principles. [6]
3.	(a)	Convert 40°C into °F. Define Ice point and steam point. Draw
		and explain with principle the Rimetallic strip thermometer. [8]
	(b)	List different manometers. Draw and explain inclined tube
9.0	ndesk	manometer and state its advantages. [8]
4.	(a)	Draw and explain force measurement using spring. List different
	iga :	types of load cells. [8]
	(b)	List diaphragm elements and state one application with
		diagram. Draw and explain torque measurement using flat spiral
		spring. [8]
5.	B	Define specific gravity. Draw and explain density measurement
ar u		using U-tube weighing system. [8]

(b) Draw and explain level to force converter and viscosity to pressure converter. [8]

Or

- 6. (a) A submarine moves horizontally in the sea and hat its axis much below the surface of sea water. A pitot take properly placed just in front of the submarine is connected to a differential pressure gauge. The pressure differential between the pitot pressure and static pressure was found to be 20 kN/m².

 Find the speed of submarine if the density of sea water is 1026 kg/m³.
 - (b) Draw and explain static vare and rotating vane systems for flow measurement. [8]

SECTION II

7. (a) An RTD has $\alpha_0 = 0.0037 \ \Omega/(\Omega/^{\circ}C)$ at $T_0 = 50^{\circ}C$, $R(50^{\circ}C) = 350 \ \Omega$. Find $R(75^{\circ}C)$. If $R(75^{\circ}C)$ is measured by passing currents of 20 hA through the RTD and if RTD has $P_D = 30 \ \text{mW/}^{\circ}C$ power dissipation, find the temperature that will be indicated by the RTD.

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(b)	Draw and explain with principle, capacitive moisture transducer.
	State its advantages and disadvantages. [9]
	Or
3. (a)	State principle of strain gauge. Define gauge factor braw and
Transon -	explain different types of strain gauges. [9]
(b)	Draw and explain with principle inductive transducers for
hally sall	displacement measurement. State its advantages and dis-
Secondari D	advantages. [9]
9. (a)	State piezoelectric phenomera and piezoelectric materials.
	Draw and explain piezoelectric transducers for force meas-
	urement. [8]
(b)	State magnetostriction phenomenon. Draw and explain with
	principle Hall effect transducer and give its applications. [8]
E gravi	Or
10. (a)	Draw and explain radioactive gauges for thickness and vacuum
Stwar (u	newurement. [8]
The state of the s	Explain photo-electric phenomenon. Draw and explain linear
10-	digital encoder for displacement measurement. [8]
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- 11. (a) Draw and explain analog and digital readout systems. State its applications.
 - (b) Draw and explain magnetic tape recorder and analog tape recorder.

Or

- 12. (a) Draw and explain the block diagram of data logger. [8]
 - (b) Enlist different digital input-output devices Draw and explain a servo-operated manometer. [8]