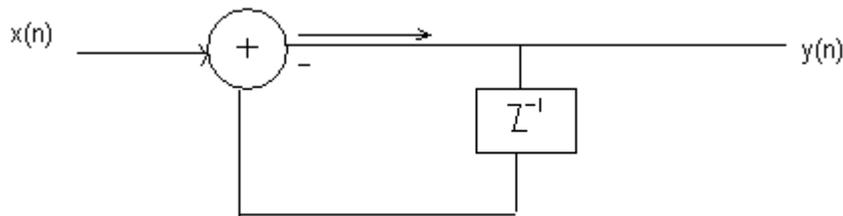


## DIGITAL SIGNAL PROCESSING

## SET - A

1. Answer the following questions.

(a). Find the response of the system, if  $a = 1$ ,  $b = -1$ ,  $x(n) = \delta(n)$  and the system is initial at rest.



(b). Find out the Nyquist rate for the signal  $x(t) = 2\% \cos(500\pi t)$

(c). What is the stability condition of an LTI system ?

(d). At which band an ideal filter is distortionless ?

(e). How the DFT and DTFT of one discrete time signal related ?

(f). Find out the impulse response of the LTI system given by

$$y(n) = k_1 x(n) + k_2 x(n-1) + k_3 x(n-2).$$

(g). What are the disadvantages of FFT over DFT ?

(h). Draw the signal flow graph of a first order digital filter.

(i). Show whether the systems are (i) Linear / Non Linear ,(ii) TV/TIV

$$y(n) = \sum_{k=-\infty}^n x(k)$$

$$y(n) = x(n^2)$$

(j). what is the aliasing effect ?

2. (a). Determine the impulse response for the given system described by difference equation

$$y(n] - 4y(n-1) + 4y(n-2) = x(n] - x(n-1)$$

(b). compute and sketch the step response of the system :

$$y(n) = 1/M \left( \sum_{k=0}^{N-1} x(n-k) \right)$$

3. (a). determine convolution of the following pairs of signal by means of ZT.

$$X_1(n) = 0.5^n u(n), \quad X_2(n) = \cos \pi n u(n)$$

(b). Consider the fir filter represented as  $y(n) = x(n) + x(n-4)$ . Compute and sketch the magnitude and phase spectrum.

4. (a). Let  $x(n]$  be a real valued  $N$  point sequence. Develop a method to compute a  $N$  point DFT  $x'(k)$ , which contains only the odd harmonics by using a real  $N/2$  point DFT.

(b). Perform linear convolution of the following sequence by overlap method.

$$x(n) = \{1, -1, 2, -2, 3, -3, 4, -4\}$$

$$h(n) = \{1, -1\}$$

5.  $x(n) = \delta(n) + 2\delta(n-1) + \delta(n-3)$

(i) Find the four point DFT of  $X(n)$ .

(ii) If  $y(n)$  is the four point circular convolution of  $x(n)$  with itself, find  $y(n)$  and four point DFT  $y(k)$ .

6. Design an FIR digital filter approximating the ideal low frequency response.

$$H_d(\omega) = \begin{cases} 1, & |\omega| \leq \pi/6 \\ 0, & \pi/6 \leq |\omega| \leq \pi \end{cases}$$

(i) Determine the coefficients of 25 tap filter based on window method with a rectangular window.

(ii). Plot the magnitude and phase response of the filter.

7. (a). With impulse invariance, a first order pole in  $H_a(s)$  at  $s = s_k$  is mapped to a pole in  $H(z)$  at  $Z = e^{s_k T}$

$$\frac{1}{s - s_k} = \frac{1}{1 - e^{s_k T} z^{-1}}$$

Determine how a second order pole is mapped with impulse variance.

(b). A second order continuous time filter has a system function

$$H(s) = 1/(s-a) + 1/(s-b)$$

where  $a < 0, b < 0$  are real. Determine the location of poles of  $H(z)$  if the filter designed using impulse invariance technique with  $T = 2$  sec.

8. (a). find the direct form II realization for the system described by difference equation.

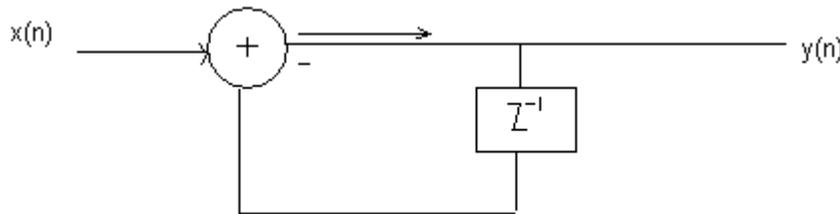
$$Y(n) = 3/4 y(n-1) + 3/4 y(n-2) + x(n) - 1/3 x(n-1)$$

(b). explain the power spectrum estimation using the Bartlett method.

### SET-B

1. Answer the following questions.

(a). Find the response of the system, if  $a = 1, b = -1, x(n) = \delta(n)$  and the system is initial at rest.



(b). Find out the Nyquist rate for the signal  $x(t) = 2 \cos(500\pi t)$

(c). What is the stability condition of an LTI system ?

(d). At which band an ideal filter is distortionless ?

(e). How the DFT and DTFT of one discrete time signal related ?

(f). Find out the impulse response of the LTI system given by

$$y(n) = k_1 x(n) + k_2 x(n-1) + k_3 x(n-2).$$

(g). What are the disadvantages of FFT over DFT ?

(h). Draw the signal flow graph of a first order digital filter.

(i). Show whether the systems are (i) Linear / Non Linear, (ii) TV/TIV

$$y(n) = \sum_{k=-\infty}^n x(k)$$

$$y(n) = x(n^2)$$

(j). what is the aliasing effect ?

2. (a). Determine the impulse response for the given system described by difference equation

$$y(n) - 4y(n-1) + 4y(n-2) = x(n) - x(n-1)$$

- (b). compute and sketch the step response of the system :

$$y(n) = 1/M \left( \sum_{k=0}^{N-1} x(n-k) \right)$$

3. (a). find the direct form II realization for the system described by difference equation.

$$Y(n) = 3/4 y(n-1) = 3/4 y(n-2) + x(n) - 1/3 x(n-1)$$

- (b). Consider the fir filter represented as  $y(n) = x(n) + x(n-4)$ . Compute and sketch the magnitude and phase spectrum.

4. (a). Let  $x(n)$  be a real valued  $N$  point sequence. Develop a method to compute a  $N$  point DFT  $x'(k)$ , which contains only the odd harmonics by using a real  $N/2$  point DFT.

- (b). Perform linear convolution of the following sequence by overlap method.

$$x(n) = \{1, -1, 2, -2, 3, -3, 4, -4\}$$

$$h(n) = \{1, -1\}$$

5.  $x(n) = \text{*****}$

- (i) Find the four point DFT of  $X(n)$ .

- (ii) If  $y(n)$  is the four point circular convolution of  $x(n)$  with itself, find  $y(n)$  and four point DFT  $y(k)$ .

6. Determine the mean and the autocorrelation of the sequence  $x(n)$ , which is the output of a ARMA (1,1) process described by difference equation

$$x(n) = 0.5 x(n-1) + w(n) - w(n-1).$$

7. For zero mean, jointly Gaussian random variable  $X_1, X_2, X_3, X_4$  it is known that  $E(X_1 X_2 X_3 X_4) = E(X_1 X_2) E(X_3 X_4) + E(X_1 X_3) E(X_2 X_4) + E(X_1 X_4) E(X_2 X_3)$

- Use this result to derive the mean square value of  $r'_{xx}(m)$  and the variance which is

$$\text{Var}[r'_{xx}(m)] = E[|r'_{xx}(m)|^2] - E[r'_{xx}(m)]^2$$

8. Determine the coefficient  $\{h(n)\}$  of a linear phase FIR of length  $N = 15$  which has a symmetric unit sample response and a frequency response that

$$H_r\left(\frac{2\pi k}{15}\right) = \begin{cases} 1, & k = 0, 1, 2, 3 \\ 0, & k = 4, 5, 6, 7 \end{cases}$$

satisfies the condition.

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