

**B. Tech Degree VI Semester (Supplementary)
Examination, September 2008**

**CS/EI/EE 601 DIGITAL SIGNAL PROCESSING
(2002 Scheme)**

Time : 3 Hours

Maximum Marks : 100

- I. (a) What is impulse response of a system and give its significance? (3)
- (b) The input sequence $\left(\underset{\uparrow}{3}, 1, 2, -1 \right)$ is applied to a discrete time processor with unit sample response $h(n) = \left(\underset{\uparrow}{1}, 2, 1 \right)$. Compute the resulting output sequence of the processor. (7)
- (c) Let $e(n)$ be an exponential sequence $e(n) = \alpha^n$ for all n , let $x(n)$ and $y(n)$ denote two arbitrary sequences. Show that $[e(n)x(n) * e(n)y(n)] = e(n)[x(n) * y(n)]$ where $*$ denotes convolution. (10)
- OR**
- II. (a) List the condition for (i) Linearity (ii) Stability (iii) Causality for an LTI system. Check the linearity, stability and causality of the system defined by $y(n) = nx(n)$. (12)
- (b) Find the Z-transform of $x(n) = \cos wn u(n)$. (8)
- III. Find the linear and circular convolution of the sequence $x(n) = \left(\underset{\uparrow}{1}, 0.5 \right)$ and $h(n) = \left(\underset{\uparrow}{0.5}, 1 \right)$ using DFT. (20)
- OR**
- IV. Compute the 8 point DFT of the sequence $x(n) = (1, 1, 1, 1, 0, 0, 0, 0)$ using decimation in time FFT algorithm. Write the necessary butterfly diagram. (20)
- V. Design a low pass FIR filter for $N=7$ and $W_c = 1 \text{ rad/sec}$ using
(i) Rectangular window (ii) Hamming window (20)
- OR**
- VI. (a) Prove that FIR filter have a linear phase characteristic for a symmetrical impulse response with even number of samples. (10)
- (b) Explain the frequency sampling method of FIR filter design. (5)
- (c) What is Cubb's phenomenon? (5)
- VII. (a) Explain the impulse invariant transformation. (10)
- (b) Convert the analog filter with system transfer function $H_a(s) = \frac{s+0.1}{(s+0.1)^2+9}$ into a digital IIR filter by means of impulse invariant transformation. (10)
- OR**
- VIII. (a) Explain the bilinear transformation. (10)
- (b) Convert the analog filter with system function $H_a(s) = \frac{s+0.3}{(s+0.3)^2+16}$ into a digital IIR filter using bilinear transformation. (10)
- IX. (a) What are the important characteristics of a DSP processor? (6)
- (b) Briefly explain any one application of digital signal processing. (14)
- OR**
- X. (a) Explain the quantization process via truncation and rounding. (12)
- (b) What is meant by limit cycle oscillation explain? (8)