

B.Tech. Degree VI Semester Examination, April 2008**CS/EC/EI/EE 601 DIGITAL SIGNAL PROCESSING**
(1999 Scheme)

Time: 3 Hours

Maximum Marks: 100

I a) Check whether the following systems are causal, time invariant, linear and stable.

i) $y(n) = ne^{x(n)}$

ii) $y(n) = \sum_{k=-\infty}^n x(k)$ (10)

b) Find the linear convolution of $x_1(n) = \{1, 2, 1, 2\}$ and $x_2(n) = \{2, 1, 2\}$ (4)c) Prove that an LTI system is stable if its impulse response $h(n)$ is absolutely summable. (6)**OR**II a) Find the input $x(n)$ of the system if the impulse response $h(n)$ and the output $y(n)$ as given below:

$$h(n) = \{1, 2, 3, 2\}$$

$$y(n) = \{1, 3, 7, 10, 10, 7, 2\}$$
 (10)

b) Find the inverse Z transform of $X(z) = \frac{1+3z^{-1}}{1+3z^{-1}+2z^{-2}}$; $|z| > 2$. (10)III Determine the response of an LTI system by radix – 2 DITFFT whose input is $x(n) = \{1, 1, 1\}$ and impulse response is $h(n) = \{-1, -1\}$. (20)**OR**IV a) Find the circular convolution of the sequences $x_1(n) = \{2, 1, 2, 1\}$ and $x_2(n) = \{1, 2, 3, 4\}$ using DFT and IDFT method. (12)

b) State and prove the time shifting property of DFT. (8)

V a) Design a low pass filter using rectangular window by taking 9 samples of $w(n)$ and with a cut off frequency of 12 rad/sec. (15)

b) What are the design steps for linear phase FIR filter design? (5)

ORVI a) An FIR filter is given by the difference equation $y(n) = 2x(n) + \frac{4}{5}x(n-1) + \frac{3}{2}x(n-2) + \frac{2}{3}x(n-3)$. Determine the lattice form. (10)

b) Design an ideal band pass filter with a frequency response

$$H_d(e^{j\omega}) = 1 \text{ for } \frac{\pi}{4} \leq |\omega| \leq \frac{3\pi}{4} = 0.$$

Otherwise Find the values of $h(n)$ for $N = 11$. (10)

(Turn Over)

- II a) Obtain the direct Form I and direct Form II realization of discrete time system represented by the transfer function::

$$H(z) = \frac{8z^3 - 4z^2 + 11z - 2}{(z - 1/4)(z^2 - z + 1/2)} \quad (10)$$

- b) What are the advantages and disadvantages of bilinear transformation? (5)
 c) Compare IIR and FIR filters. (5)

OR

- III Design a Butterworth IIR digital filter using bilinear transformation for the specifications :

$$\begin{aligned} \frac{1}{\sqrt{2}} \leq |H(\omega)| \leq 1.0 & ; 0 \leq \omega \leq 0.2\pi \\ |H(\omega)| \leq 0.08 & ; 0.4\pi \leq \omega \leq \pi \end{aligned} \quad (20)$$

- IV a) Draw and explain the block diagram of a typical DSP processor. (12)
 b) Discuss any two applications of DSP. (8)

OR

- a) Explain the effects due to truncation rounding and quantisation in IIR Systems. (12)
 b) What is meant by limit cycle? How it can be eliminated? (8)

